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OPTICAL ELEMENT AND OPTICAL APPARATUS

BACKGROUND OF THE INVENTION

Field of the Invention

5 The present invention relates to an optical element and optical apparatus and, more particularly, to an optical element and optical apparatus suitably applicable, for example, to video cameras, still video cameras, copiers, and so on.

10 Related Background Art

 An inverted, real image system without intermediate image formation is principally used as an optical system in the conventional optical apparatus for forming an image of an object on the final image
15 plane.

 On the other hand, an optical system with intermediate image formation is used when a small cross section is desired for the optical system or when an erect image is demanded.

20 Fig. 6A to Fig. 6C are conceptual drawings of such optical systems. Fig. 6A and Fig. 6B are conceptual drawings where intermediate image formation is brought about in a coaxial system.

 In Fig. 6A, reference numeral 1 designates the
25 object plane and 5 an optical system, the system 5 being comprised of lens systems L1, L3, and L2. Numeral 2 denotes an intermediate image plane, the

plane 2 being located inside the lens system L3.

Numeral 3 represents the final image plane.

In the same figure, lights from the object 1 are condensed by the lens system L1 to be focused on the intermediate image plane 2 inside the lens system L3 and form an inverted object image (intermediate image) on the plane 2, and thereafter the lights are condensed by the lens system L2 to be focused on the final image plane 3 and form an erect object image thereon.

In this example, the lens system L1 composes an object-side imaging element for forming the image of the object 1 on the intermediate image plane 2 in the lens system L3, and the lens system L2 composes an image-side imaging element for reimaging the image on the intermediate image plane 2, on the final image plane 3.

Each of these imaging elements composes a part of the imaging optical system 5. The lens system L3 herein conceptually represents the optical system corresponding to a field lens, a prism block, or the like.

Fig. 6B is a major-part sectional view of an erect, real image forming system using a medium having a nonuniform index profile. In the same figure lights from the object 1 are condensed by a front portion 10 of the imaging optical system (optical system) 5 to form an image on the intermediate image plane and

thereafter they are focused by a rear portion 11 of the imaging optical system 5 to form an object image on the final image plane 3. In this case, the front portion 10 composes the object-side imaging part element and the rear portion 11 the image-side imaging element. These together compose the imaging optical system 5. A lens array, in which lenses composed of such erect 1:1 imaging systems using the medium with the nonuniform index profile are arrayed, is used in the copiers and other equipment.

Fig. 6C is a major-part schematic diagram to show an optical apparatus having a non-coaxial, optical system and an intermediate image plane therein, as disclosed in Japanese Patent Application Laid-open No. 8-292371. In the same figure, lights from the object 1 pass through an aperture stop 4 and thereafter are incident to an entrance surface 10-1 of optical element 5 to be refracted into the element 5. They are then reflected by a concave, reflective surface 10-2 and thereafter focused on the intermediate image plane 2. The lights from the intermediate image plane 2 are thereafter reflected by reflective surfaces 11-1, 11-2, 11-3 to propagate inside the element 5 and emerge from an exit surface 11-4, then forming the object image on the final image plane 3.

In Fig. 6C, the concept of reference axis (8-1 to 8-5) is employed in correspondence to the optic axis of

the coaxial system. This reference axis is defined as an optical path of a reference-wavelength ray traveling via the center of the object 1 and the center (of the aperture) of the stop 4.

5 This optical system is called an off-axial, optical system because the optical system includes a surface in which at an intersecting point between the reference axis corresponding to the optic axis and the component surface the reference axis does not agree
10 with the normal to the surface but makes a finite angle except for 0 therewith (the definition of the off-axial, optical system). Surfaces of this type are called off-axial surfaces or off-axial curved surfaces. In this case, the imaging optical system 5 is also
15 composed of a front element 10 (the surfaces 10-1, 10-2) composing the object-side imaging element and a rear element 11 (the surfaces 11-1, 11-2, 11-3, 11-4) composing the image-side imaging element, the elements 10, 11 being incorporated.

20 The non-coaxial, off-axial, optical system is described in detail in Japanese Patent Application Laid-open No. 9-5650, including the setting method of surface shapes and the calculating method of paraxial amounts together with properties of the off-axial,
25 optical system.

 Although Figs. 6A, 6B, 6C show the examples where single intermediate imaging is achieved, for

simplicity, there are known systems involving a plurality of (two or more) intermediate imaging procedures.

5 The optical systems involving the intermediate
imaging often adopt a designing approach for retaining
the imaging performance, including spherical
aberration, on the intermediate image plane and
maintaining this performance so as to keep the imaging
performance on the final image plane. This approach is
10 conceptually easy to understand and also easy to
design, because the approach includes use of some
normal designing techniques. In the case of design
using the automatic designing approach, the design is
sometimes conducted normally with no consideration on
15 imaging characteristics on the intermediate image plane
at all but with only consideration on the imaging
characteristics on the final image plane.

Even in such cases, however, one can often reach a
solution that retains some imaging characteristics,
20 including spherical aberration, on the intermediate
image plane.

In general, there exist foreign materials such as
dust particles, and bubbles in the optical elements.
Sizes of these are various, but the standards of Glass
25 Industry Association include the standard of bubble for
30 μm and greater bubbles in the optical elements. In
the case of special, visual type lenses, even a bubble

or a particle as fine as 30 μm or less would pose a problem, so that special inspection is needed for such lenses.

5 The limit of detection of a bubble or a particle
by naked eyes is about 5 μm , and those having the size
of about 100 μm first become capable of visual
detection. For the surface reflectors, a flaw, a
deposit, or the like on the surface is also a cause of
degrading the optical performance and inspection
10 thereof is necessary. The sizes of the bubbles and
particles in the optical elements and the widths of
flaws or the sizes of the deposits or the like on the
reflective surfaces, which could pose a problem, vary
depending upon design specifications and manufacturing
15 cost, but, with emphasis on the manufacturing cost, a
product is determined to be defective if there are many
100 μm - and greater bubbles or particles, or flaws,
deposits or the like on the reflective surface, which
can be detected visually. With emphasis on the optical
20 performance, because the bubbles, particles, deposits,
and flaws having the sizes or widths of 10 μm or less
are considered not to affect the optical performance,
it seems valid to make the determination of defective
if there are many bubbles, particles, deposits, flaws,
25 etc. having the sizes of 10 μm and above. As described
above, the sizes of the bubbles, particles, deposits,
etc. to be criteria of inspection are approximately 10

to 100 μm .

The sizes of the bubbles, particles, deposits, etc. posing the problem will be described from the aspect of specifications of product. In general, the sizes of the bubbles, particles, deposits, etc. posing the problem on an image pickup device vary depending upon types of products, types of images, or individuals, but an eyesore often starts when the size of an image of the bubble, particle, deposit, etc. on a photoreceptive surface of the image pickup device in an in-focus state exceeds approximately five times (5b) the length of the minimum resolution (b) given by the size of pixels of the image pickup device or the like. This numeral of 5 is one figured out by experiments with plural types of images against plural subjects and corresponds to the fact that a drop of one pixel or so is not offensive to the eye, but about five times one pixel often becomes offensive.

Accordingly, in Figs. 6A to 6C, when the intermediate image plane 2 is imaged on the final image plane 3 where the image pickup device is located and when β_{11} represents the image magnification of the lens system 11 of the image-side imaging element, the size of a noise source posing the problem near the intermediate image plane 2 is not less than approximately the following:

$$5b/|\beta_{11}| \quad (\text{Eq 1}).$$

In this equation, $|\beta_{11}|$ indicates an absolute value of the image magnification β_{11} of the lens system 11 being the image-side imaging element. For example, supposing the pixel size of CCD being the image pickup device is 5 μm square and β_{11} is 1, the size of the noise source posing the problem near the intermediate image plane is not less than 25 μm .

Particularly, in the optical systems arranged to form the intermediate image plane in the lens system, in the optical block, or the like, if there exists a noise source, such as a dust particle, a bubble, or a flaw, irrelevant to an image (object image) desired to be transmitted to near the intermediate image position, the noise source will be a cause of heavily degrading the optical performance.

If the noise from such a noise source overlies an image (signal) on the photoreceptive surface of the image pickup device being the final image plane, there will arise a problem that the image becomes harder to see. Specific examples of the dust, bubble, or flaw irrelevant to the desired-to-transmit image include the dust particles or bubbles (indicated by NO in the drawing) in the internally solid optical member near the intermediate image plane 2, as shown in the system (coaxial system) of Fig. 7A and in the system (non-coaxial system) of Fig. 7B, and the flaws (indicated by NO in the drawing) on a component surface of the

optical system near the intermediate image plane 2, as shown in the system (coaxial system) of Fig. 7C and in the system (non-coaxial, off-axial, optical system) of Fig. 7D.

5 Another special noise source is a streak pattern C of steps of a Fresnel lens or diffraction type lens where the Fresnel lens or diffraction type lens is used as a field lens 12 as shown in Fig. 7E.

10 In general, a popular method for making such a noise source as the dust, bubble, or flaw inoffensive was a method for designing the intermediate image plane to be located in air and thereby keeping the noise source, existing in the optical medium, on the surface thereof, or on the reflective surface, in a defocus state, as described, for example, in Japanese Patent
15 Application Laid-open No. 6-265814.

 However, the problem was that this method for making the noise source inoffensive by defocus was not applicable to optical systems downsized by integrally
20 forming the optical medium and forming the intermediate image therein as described in Japanese Patent Application Laid-open No. 8-292371, because there was no air layer inside.

 Japanese Patent Application Laid-open No. 6-265814
25 also describes an example in which aberration such as spherical aberration is intentionally brought about on the intermediate image plane, so as to make the streaks

of the Fresnel lens as a field lens inoffensive. This method for generating aberration, however, generates the aberration by use of a rotationally symmetric system, so that the aberration is the third or higher order aberration. This method thus had the problem that the effect appeared weaker in a dark optical system, particularly in an optical system stopped down or the like, than in the method by defocus which worked in the first order.

10 In the case where the intermediate image moves depending upon zoom positions as described in Japanese Patent Application Laid-open No. 8-292372, even if the intermediate image at a certain zoom position is in air, the intermediate image plane at another zoom position could be near the surface of the component surface or in the optical medium. In that case there arose the problem that the noise source was unable to be made inoffensive at the zoom position.

20 In the case where the focal length is constant but the object distance varies, the final image plane can be kept aligned by focusing, but the position of the intermediate image plane also varies on that occasion. Therefore, even if at a certain object distance the intermediate image is in air by defocus, the intermediate image plane at another object distance could be near the surface of the component surface or in the medium. In that case there arose the problem

that the noise source was unable to be made inoffensive at that object distance.

Accordingly, in Figs. 6A to 6C, when the intermediate image plane 2 is imaged on the final image plane 3 where the image pickup device is located and when β_{11} represents the image magnification of the lens system 11 of the image-side imaging element, the size of the noise source posing the problem near the intermediate image plane 2 is not less than approximately the following:

$$5b/|\beta_{11}| \quad (\text{Eq 1}).$$

In this equation, $|\beta_{11}|$ indicates the absolute value of the image magnification β_{11} of the lens system 11 being the image-side imaging element. For example, supposing the pixel size of CCD being the image pickup device is 5 μm square and β_{11} is 1, the size of the noise source posing the problem near the intermediate image plane is not less than 25 μm .

SUMMARY OF THE INVENTION

An object of the present invention is to provide an optical element and optical apparatus capable of obtaining a good image on the final image plane even if a noise source exists at and/or near the intermediate image position.

An optical element of the present invention is:

(1-1) an optical element comprising an object-side

imaging element for imaging an object on an intermediate image plane in an optical path and an image-side imaging element for reimaging an object image formed on the intermediate image plane, on a
5 final image plane, wherein at least one of said object-side imaging element and said image-side imaging element comprises an off-axial curved surface, and wherein aberration is generated by both of the object-side imaging element and the image-side imaging
10 element, so as to flatten (disturbance of) a light intensity distribution on the final image plane, caused by a noise source at or near the intermediate image plane;

(1-2) an optical element in which an object image
15 is formed on an intermediate image plane by reflecting a light incident from an object through an entrance plane by at least one reflective surface of a plurality of reflective surfaces and in which a light from the object image is reflected by the remaining reflective
20 surface or surfaces out of said plurality of reflective surfaces to be made emergent from an exit plane and to be directed onto a predetermined plane, wherein at least one of an object-side imaging element ranging from the entrance plane to the intermediate image plane
25 and an image-side imaging element ranging from the intermediate image plane to the exit plane comprises an off-axial curved surface and wherein aberration is

generated by both of said object-side imaging element and said image-side imaging element, so as to flatten a light intensity distribution produced on the predetermined plane by a noise source at or near the intermediate image plane; or

(1-3) an optical element in which an object image is formed on an intermediate image plane by reflecting a light incident from an object through an entrance surface provided in a surface of a transparent body by at least one reflective surface of a plurality of reflective surfaces provided in the surface of the transparent body and in which a light from the object image is reflected by the remaining reflective surface or surfaces out of said plurality of reflective surfaces to be made emergent from an exit surface provided in the surface of the transparent body and to be directed onto a predetermined plane, wherein at least one of an object-side imaging element present from the entrance surface to the intermediate image plane and an image-side imaging element present from the intermediate image plane to the exit surface comprises an off-axial curved surface and wherein aberration is generated by both of said object-side imaging element and said image-side imaging element, so as to flatten a light intensity distribution produced on the predetermined plane by a noise source at or near the intermediate image plane.

Particularly, in the compositions (1-1) to (1-3), the optical element is characterized in that:

(1-3-1) said aberration is generated so as to degrade imaging performance of said object-side imaging element and so as to correct the imaging performance thus degraded, by said image-side imaging element;

(1-3-2) said off-axial curved surface is provided in at least one reflective surface out of said plurality of reflective surfaces;

(1-3-3) said optical element has a stop, and the following relation is satisfied:

$$V/|\beta_{11}| < U$$

where β_{11} is an image magnification of said image-side imaging element, V a spot size on the final image plane at a fixed aperture diameter of said stop, and U a spot size on said intermediate image plane;

(1-3-4) said optical element has a stop, and the following relation is satisfied:

$$3 \cdot V/|\beta_{11}| < U$$

where β_{11} is an image magnification of said image-side imaging element, V a spot size on the final image plane at a fixed aperture diameter of said stop, and U a spot size on said intermediate image plane;

(1-3-5) said optical element has a stop, and the following relation is satisfied:

$$5 \cdot V/|\beta_{11}| < U$$

where β_{11} is an image magnification of said image-side

imaging element, V a spot size on the final image plane at a fixed aperture diameter of said stop, and U a spot size on said intermediate image plane;

(1-3-6) degradation of the imaging performance of
5 said object-side imaging element is achieved by
generating specific aberration independent of a field
angle from on the axis to off the axis;

(1-3-7) said specific aberration is on-axis
astigmatism;

10 (1-3-8) degradation of the imaging performance of
said object-side imaging element is achieved by such
aberration of torsion that rays in a meridional section
jump out of the meridional section, which is generated
independent of the field angle from on the axis to off
15 the axis;

(1-3-9) a diameter of a spot near said
intermediate image plane is two or more times a minimum
diameter of said noise source posing a problem even
when the system is at a minimum aperture value;

20 (1-3-10) a diameter of a spot near said
intermediate image plane is three or more times a
minimum diameter of said noise source posing a problem
even when the system is at a minimum aperture value;

(1-3-11) a diameter of a spot near said
25 intermediate image plane is three or more times a
minimum diameter of said noise source posing a problem
when the system is at a full aperture;

(1-3-12) a diameter of a spot near said intermediate image plane is five or more times a minimum diameter of said noise source posing a problem when the system is at a full aperture;

5 (1-3-13) said optical element is constructed in a structure in which a focal length thereof is invariant;

(1-3-14) at least one of said object-side imaging element and image-side imaging element has a surface having anamorphic powers, wherein

10
$$P = 1/f$$

P : power, f : focal length;

(1-3-15) at least one of said object-side imaging element and image-side imaging element is comprised of an optical system having no common symmetry plane;

15 (1-3-16) at least one of said object-side imaging element and image-side imaging element comprises a surface with no symmetry at all; and so on.

An optical apparatus of the present invention is characterized in that:

20 (2-1) the object is imaged on a photoreceptive surface of an image pickup device by use of the optical element of either one of the compositions (1-1) to (1-3); or

(2-2) the apparatus comprises at least two optical
25 elements of the compositions (1-1) to (1-3), relative positions are changed between said at least two optical elements, whereby the object is imaged at different

magnifications on an image pickup device.

Particularly, in the composition (2-1) or (2-2), the optical apparatus is characterized in that:

(2-2-1) a stop is provided near the entrance
5 surface of said optical element and the following relation is satisfied:

$$10 \cdot b / |\beta_{11}| < SD$$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a
10 size of a pixel of said image pickup device when said stop is at a minimum aperture value, and β_{11} an image magnification of said image-side imaging element;

(2-2-2) a stop is provided near the entrance
15 surface of said optical element and the following relation is satisfied:

$$15 \cdot b / |\beta_{11}| < SD$$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a
20 size of a pixel of said image pickup device when said stop is at a minimum aperture value, and β_{11} an image magnification of said image-side imaging element;

(2-2-3) a stop is provided near the entrance
surface of said optical element and the following relation is satisfied:

25 $15 \cdot b / |\beta_{11}| < SD$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a

size of a pixel of said image pickup device when said stop is at a full aperture value, and β_{11} an image magnification of said image-side imaging element;

(2-2-4) a stop is provided near the entrance
5 surface of said optical element and the following relation is satisfied:

$$25 \cdot b / |\beta_{11}| < SD$$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a
10 size of a pixel of said image pickup device when said stop is at a full aperture value, and β_{11} an image magnification of said image-side imaging element;

(2-2-5) change of the relative positions between said at least two optical elements is achieved by
15 displacing at least one of said optical elements in a direction of a reference axis; and so on.

An optical system of the present invention is:

(3-1) an optical system comprising an object-side imaging element for once imaging an object on an
20 intermediate image plane in an optical path and an image-side imaging element for reimaging an object image formed on the intermediate image plane, on a final image plane, wherein at least one of said object-side imaging element and said image-side imaging
25 element comprises an off-axial curved surface, and wherein aberration is generated by both of the object-side imaging element and the image-side imaging

element, so as to flatten (disturbance of) a light intensity distribution on the final image plane, caused by a noise source at or near the intermediate image plane.

5 Particularly, the optical system is characterized in that:

 (3-1-1) said off-axial curved surface is comprised of a reflective surface;

 (3-1-2) said aberration is generated so as to
10 degrade imaging performance of said object-side imaging element and so as to correct the imaging performance thus degraded, by said image-side imaging element;

 (3-1-3) said optical system has a stop, and the following relation is satisfied:

15
$$V/|\beta_{11}| < U$$

where β_{11} is an image magnification of said image-side imaging element, V a spot size on the final image plane at a fixed aperture diameter of said stop, and U a spot size on said intermediate image plane;

20 (3-1-4) said optical system has a stop, and the following relation is satisfied:

$$3 \cdot V/|\beta_{11}| < U$$

where β_{11} is an image magnification of said image-side imaging element, V a spot size on the final image plane
25 at a fixed aperture diameter of said stop, and U a spot size on said intermediate image plane;

 (3-1-5) said optical system has a stop, and the

following relation is satisfied:

$$5 \cdot V / |\beta_{11}| < U$$

where β_{11} is an image magnification of said image-side imaging element, V a spot size on the final image plane at a fixed aperture diameter of said stop, and U a spot size on said intermediate image plane;

(3-1-6) degradation of the imaging performance of said object-side imaging element is achieved by generating specific aberration independent of a field angle from on the axis to off the axis;

(3-1-7) said specific aberration is on-axis astigmatism;

(3-1-8) degradation of the imaging performance of said object-side imaging element is achieved by such aberration of torsion that rays in a meridional section jump out of the meridional section, which is generated independent of the field angle from on the axis to off the axis;

(3-1-9) a diameter of a spot near said intermediate image plane is two or more times a minimum diameter of said noise source posing a problem even when the system is at a minimum aperture value;

(3-1-10) a diameter of a spot near said intermediate image plane is three or more times a minimum diameter of said noise source posing a problem even when the system is at a minimum aperture value;

(3-1-11) a diameter of a spot near said

intermediate image plane is three or more times a minimum diameter of said noise source posing a problem when the system is at a full aperture;

(3-1-12) a diameter of a spot near said
5 intermediate image plane is five or more times a minimum diameter of said noise source posing a problem when the system is at a full aperture;

(3-1-13) said optical system is a unifocal system in which a focal length thereof is invariant;

10 (3-1-14) at least one of said object-side imaging element and image-side imaging element has a surface having anamorphic powers;

(3-1-15) at least one of said object-side imaging element and image-side imaging element is comprised of
15 an optical system having no common symmetry plane;

(3-1-16) at least one of said object-side imaging element and image-side imaging element comprises a surface with no symmetry at all; and so on..

An optical apparatus of the present invention is
20 characterized in that:

(4-1) the object is imaged on a photoreceptive surface of an image pickup device by use of the optical system of the composition (3-1); or

(4-2) the optical apparatus comprises at least one
25 optical system of the composition (3-1), and at least one of a focal length, an image magnification, and a focus on the final image plane is variable.

Particularly, in the composition (4-1) or (4-2), the optical apparatus is characterized in that:

(4-2-1) a stop is provided near the entrance surface of said optical system and the following
5 relation is satisfied:

$$10 \cdot b / |\beta_{11}| < SD$$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a size of a pixel of said image pickup device when said
10 stop is at a minimum aperture value, and β_{11} an image magnification of said image-side imaging element;

(4-2-2) a stop is provided near the entrance surface of said optical system and the following relation is satisfied:

15 $15 \cdot b / |\beta_{11}| < SD$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a size of a pixel of said image pickup device when said
stop is at a minimum aperture value, and β_{11} an image
20 magnification of said image-side imaging element;

(4-2-3) a stop is provided near the entrance surface of said optical system and the following relation is satisfied:

$$15 \cdot b / |\beta_{11}| < SD$$

25 where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a size of a pixel of said image pickup device when said

stop is at a full aperture value, and β_{11} an image magnification of said image-side imaging element;

(4-2-4) a stop is provided near the entrance surface of said optical system and the following

5 relation is satisfied:

$$25 \cdot b / |\beta_{11}| < SD$$

where SD is a spot diameter on said intermediate image plane, b a length of a minimum resolution given by a size of a pixel of said image pickup device when said
10 stop is at a full aperture value, and β_{11} an image magnification of said image-side imaging element;

(4-2-5) change of relative positions between said at least two optical systems or between the optical system and the image plane is achieved by displacing at
15 least one of said optical system and the image plane in a direction of a reference axis;

(4-2-6) change of at least one of said focal length, image magnification, and focus on the final image plane, of said optical system, is achieved by
20 changing a distance of a certain portion of the optical system relative to the final image plane along a reference axis; and so on.

An optical element of the present invention is characterized in that:

25 (5-1) said optical system of the composition (3-1) is a reflecting optical system wherein the light from the object is made incident through an entrance surface

formed in a surface of a transparent body thereinto,
light propagating inside said transparent body is
reflected by one or more reflective surfaces comprised
of curved surfaces provided in said transparent body,
5 and the light is made emergent from an exit surface of
the transparent body to form an image, or a reflecting
optical system wherein the light from the object is
reflected by a plurality of reflective surfaces
comprised of reflective mirrors and thereafter the
10 light is emergent therefrom;

(5-2) said optical system of the composition (5-1)
is an optical element integrally formed; or

(5-3) said optical system of the composition (5-1)
comprises a plurality of optical elements integrally
15 formed.

Particularly, in the compositions (5-1) to (5-3),
the optical system is characterized in that:

(5-3-1) the following condition is satisfied:

$$20 \quad \left| \frac{D \cdot f_1}{S \cdot AR_1} \right| < 0.1 \quad (1a)$$

where D is a size of a bubble, a dust particle, or the
like posing a problem in terms of optical performance
and existing inside said optical element or a width of
a flaw or a size of a deposit or the like posing a
25 problem in terms of optical performance and existing on
a reflective surface near the intermediate image
position, f_1 is a maximum synthetic focal length out of

those dependent upon azimuths, of a region from the entrance surface located nearest to the object to an optical surface before the intermediate image position, an azimuth at that time being defined as ξ , S is an on-axis astigmatic difference at the intermediate image position, and AR1 is a diameter of an exit pupil from the entrance surface nearest to the object to the optical surface before said intermediate image position in correspondence to said azimuth ξ and at a full aperture of the stop;

(5-3-2) the optical system has a function to adjust an aperture diameter of the stop, and the following condition is satisfied:

$$\left| \frac{D \cdot f_1}{S \cdot AR_2} \right| < 0.3 \quad (2a)$$

where D is a size of a bubble, a dust particle, or the like posing a problem in terms of optical performance and existing inside said optical element or a width of a flaw or a size of a deposit or the like posing a problem in terms of optical performance and existing on a reflective surface near the intermediate image position, f_1 is a maximum synthetic focal length out of those dependent upon azimuths, of a region from the entrance surface located nearest to the object to an optical surface before the intermediate image position, an azimuth at that time being defined as ξ , S is an on-axis astigmatic difference at the intermediate image

position, and AR2 is a diameter of an exit pupil from the entrance surface nearest to the object to the optical surface before said intermediate image position in correspondence to said azimuth ξ and at a small aperture of the stop;

(5-3-3) the following condition is satisfied:

$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR_1} \right| < 0.1 \quad (3a)$$

where f_1 is a maximum synthetic focal length out of those dependent on azimuths, of a region from the entrance surface of said optical system nearest to the object to an optical surface before the intermediate image position, an azimuth at that time being defined as ξ , S is an on-axis astigmatic difference at the intermediate image position, b is a length of a minimum resolution given by a size of a pixel of an image pickup device or the like, β is an image magnification when the intermediate image plane is imaged on the final image plane, in a direction normal to the azimuth ξ in the optical system of from the intermediate image position to the final image position on which the image pickup device is located, and AR_1 is a diameter of an exit pupil of the region from the entrance surface nearest to the object to the optical surface before the intermediate image position in correspondence to said azimuth ξ and at a full aperture of the stop;

(5-3-4) said optical system having a function to

adjust an aperture diameter, wherein the following condition is satisfied:

$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR_2} \right| < 0.3 \quad (4a)$$

5 where f_1 is a maximum synthetic focal length out of those dependent on azimuths, of a region from the entrance surface of said optical system nearest to the object to an optical surface before the intermediate image position, an azimuth at that time being defined
10 as ξ , S is an on-axis astigmatic difference at the intermediate image position, b is a length of a minimum resolution given by a size of a pixel of an image pickup device or the like, β is an image magnification when the intermediate image plane is imaged on the
15 final image plane, in a direction normal to the azimuth ξ in the optical system of from the intermediate image position to the final image position on which the image pickup device is located, and AR_2 is a diameter of an exit pupil of the region from the entrance surface
20 nearest to the object to the optical surface before the intermediate image position in correspondence to said azimuth ξ and at a small aperture of the stop.

(5-4) In the compositions (5-1) to (5-3-4), the entrance surface of the optical element being said
25 transparent body is a rotationally symmetric surface.

(5-5) In the compositions (5-1) to (5-3-4), the entrance surface of the optical element being said

transparent body is a rotationally asymmetric surface.

(5-6) In the compositions (5-1) to (5-5), the stop is disposed near the entrance surface nearest to the object in said optical system.

5 (5-7) In the compositions (5-1) to (5-6), the reflective surface of a curved surface, which is the first surface when counted from the object side of said optical system, has converging action.

10 (5-8) In the compositions (5-1) to (5-7), the exit surface of the optical element being said transparent body has a rotationally symmetric shape with respect to a reference axis.

15 (5-9) In the compositions (5-1) to (5-7), the exit surface of the optical element being said transparent body has a rotationally asymmetric shape with respect to a reference axis.

20 (5-10) In the compositions (5-1) to (5-9), the optical element is arranged to move in parallel to a direction of a reference axis emerging therefrom, thereby achieving focusing.

(5-11) In the compositions (5-3) to (5-10), the optical system is a reflection type zoom optical system wherein the object is imaged through a plurality of optical elements and zooming is achieved by changing relative positions of at least two optical elements out of said plurality of optical elements.

(5-12) An image pickup apparatus has the

reflecting optical system of the composition (5-1) to (5-11) and the object is imaged on an image pickup surface thereof.

(5-13) An observation apparatus is arranged to
5 observe the object by the optical system of the composition (5-1) to (5-11).

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1A and Fig. 1B are schematic diagrams of
10 major part of Embodiment 1 according to the present invention;

Fig. 2A and Fig. 2B are schematic diagrams of major part of Embodiment 2 according to the present invention;

15 Fig. 3A, Fig. 3B, and Fig. 3C are conceptual drawings for explaining "aberration of torsion" according to the present invention;

Fig. 4A, Fig. 4B, and Fig. 4C are schematic diagrams of major part of Embodiment 3 according to the
20 present invention;

Fig. 5 is a schematic diagram to show the relation between diameter of noise source and number (density) of noise source;

Fig. 6A, Fig. 6B, and Fig. 6C are conceptual
25 drawings of the conventional imaging systems involving intermediate imaging;

Fig. 7A, Fig. 7B, Fig. 7C, Fig. 7D, and Fig. 7E

are conceptual drawings for explaining the noise sources present at the intermediate image position in the conventional systems;

Fig. 8 is a conceptual drawing of lateral aberration according to the present invention;

Fig. 9 is an optical, sectional view in the YZ plane of Embodiment 4 of the present invention;

Figs. 10A, 10B, 10C, 10D, 10E, 10F, 10G, 10H, 10I, 10J, 10K and 10L are lateral aberration diagrams of Embodiment 4;

Fig. 11 is an optical, sectional view in the YZ plane of Embodiment 5 of the present invention;

Figs. 12A, 12B, 12C, 12D, 12E, 12F, 12G, 12H, 12I, 12J, 12K and 12L are lateral aberration diagrams of Embodiment 5;

Fig. 13 is an optical, sectional view in the YZ plane of Embodiment 6 of the present invention;

Figs. 14A, 14B, 14C, 14D, 14E, 14F, 14G, 14H, 14I, 14J, 14K and 14L are lateral aberration diagrams of Embodiment 6;

Fig. 15 is an optical, sectional view in the YZ plane of Embodiment 7 of the present invention;

Figs. 16A, 16B, 16C, 16D, 16E, 16F, 16G, 16H, 16I, 16J, 16K and 16L are lateral aberration diagrams of Embodiment 7;

Figs. 17A, 17B and 17C are optical, sectional views in the YZ plane of Embodiment 8 of the present

invention;

Figs. 18A, 18B, 18C, 18D, 18E, 18F, 18G, 18H, 18I, 18J, 18K and 18L are lateral aberration diagrams (at the wide-angle extreme) of Embodiment 8;

5 Figs. 19A, 19B, 19C, 19D, 19E, 19F, 19G, 19H, 19I, 19J, 19K and 19L are lateral aberration diagrams (at a middle position) of Embodiment 8;

Figs. 20A, 20B, 20C, 20D, 20E, 20F, 20G, 20H, 20I, 20J, 20K and 20L are lateral aberration diagrams (at
10 the telephoto extreme) of Embodiment 8;

Fig. 21 is an optical, sectional view in the YZ plane of Embodiment 9 of the present invention;

Figs. 22A, 22B, 22C, 22D, 22E, 22F, 22G, 22H, 22I, 22J, 22K and 22L are lateral aberration diagrams of
15 Embodiment 9;

Fig. 23 is an explanatory drawing of a coordinate system in the embodiments of the present invention;

Fig. 24 is a diagram of smallest spots at the intermediate image position in the conventional
20 example;

Fig. 25 is a diagram of smallest spots at the intermediate image position in Embodiment 4;

Fig. 26 is a diagram of smallest spots at the intermediate image position on the occasion of a small
25 aperture in the conventional example;

Fig. 27 is a diagram of smallest spots at the intermediate image position on the occasion of a small

aperture in Embodiment 5; and

Fig. 28 is a diagram of light spots on a reflective surface near the intermediate image plane in Embodiment 9.

5

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

In each of the embodiments described below, there is described an example wherein means for flattening (disturbance of) light intensity distribution due to the noise source in the optical apparatus is optical means for flattening the disturbance of light intensity distribution on the final image plane due to the noise source by degrading the imaging performance at the intermediate image position with respect to the imaging performance on the final image plane.

Specifically speaking, degrading the imaging performance on the intermediate image plane with respect to that on the final image plane is, for example, "that when β_{11} represents the image magnification of the image-side imaging (part) element 11 where the intermediate image plane 2 is imaged on the final image plane 3 on which the image pickup device is located and when V represents a spot size on the final image plane where the aperture diameter is fixed, data of the components of the imaging optical system 5 (surface shapes, surface separations, a refractive index, and angles between the surfaces and

the reference axis) is designed so that the spot size U on the intermediate image plane is deliberately larger than $V/|\beta_{11}|$, preferably larger than $3V/|\beta_{11}|$, more preferably larger than $5V/|\beta_{11}|$."

5 Here, the number of 3 times is a numeral corresponding to the case where the effect of the noise source is controlled to about 11 %, and the number of 5 times is a numeral corresponding to the case where the effect of the noise source is controlled to about 4 %;
10 these numerals are empirically obtained numerals respectively corresponding to a level where the effect can be recognized first with attention and to a level where the effect is little recognized even with attention.

15 Let us here define the term "spot size" used in the present invention. In the present invention, the "spot size" is defined as follows: "when 90 % of lights from one object point (90 % of light intensity) is included in a circle of a radius $A_0/2$ drawn about the
20 position of the center of gravity of a spot diagram, this A_0 is called the spot size."

 Fig. 1A is a sectional view of major part of an embodiment of an optical system according to the present invention, also illustrating optical paths.
25 Fig. 1B is spot diagrams in the optical paths of Fig. 1A. Numeral 1 designates the object plane. Numeral 5 represents an optical element in which a plurality of

reflective surfaces having respective curvatures
(curved surfaces) are integrally formed, which composes
an element of the imaging optical system. The optical
element 5 has an entrance refractive surface 10-1, four
5 reflective surfaces including mirror 10-2, mirror 10-3,
mirror 11-1, and mirror 11-2, and an exit refractive
surface 11-3 formed in order along the reference-axis
ray from the object side in the surface of a
transparent body (optical material), thus forming a
10 non-coaxial, off-axial, optical system.

Numeral 2 denotes an intermediate image plane,
which is located in the internally solid optical
material. Refractive powers of the respective entrance
surface 10-1, exit surface 11-3, and reflective
15 surfaces 10-2, 10-3, 11-1, 11-2 forming the optical
element 5 may be either positive or negative. In the
following description these will also be called simply
"surfaces."

The surfaces 10-1, 10-2, 10-3 compose the object-
20 side imaging element (front element) 10, while the
surfaces 11-1, 11-2, 11-3 compose the image-side
imaging element (rear element) 11.

Numeral 3 denotes the final image plane, on which
the image pickup surface of the image pickup device
25 such as CCD is located. Numeral 4 indicates an
aperture stop located on the object side of the optical
element 5, and La represents the reference axis of the

optical system.

Next described is the imaging action in the present embodiment. Light from the object 1 (hereinafter referred to as "object light") is regulated in an amount of incident light by the stop 4 and thereafter the object light is incident to the entrance refractive surface 10-1 of the optical element 5 to be refracted thereby, then propagate inside the element 5, and reach the concave mirror 10-2.

10 The concave mirror 10-2 reflects the object light toward the convex mirror 10-3 and the object (image) is primarily imaged on the intermediate image plane 2 by the power of the concave mirror 10-2.

By forming the object image in the optical element 5 in the early stage in this way, increase is restricted in ray-effective diameters of the surfaces positioned on the image side of the stop 4.

The object light primarily focused on the intermediate image plane 2 is then reflected by the concave mirror 11-1 and by the concave mirror 11-2 in order to be affected by the powers of the respective reflective mirrors, and the object light then reaches the exit refractive surface 11-3 to be refracted thereby, then going out of the optical element 5. Then the object light is focused on the final image plane 3.

As described above, the optical element 5 allows the object light to propagate inside with repetitively

being reflected by the plural reflective mirrors
(reflective surfaces) having the respective curvatures
and functions as a very thin lens unit in the X-
direction and in the Z-direction while having desired
5 optical performance and the imaging action as a whole.

In the present optical system, focusing is
achieved by moving the optical element 5 in the
direction parallel to the entrance reference axis
thereof.

10 Figs. 1A and 1B show an example of the optical
system of the present invention, and the present
invention also involves other optical systems,
including an optical system in which there are a
plurality of optical elements wherein a plurality of
15 reflective surfaces having respective curvatures are
integrally formed, a variable-power optical system with
a plurality of optical elements for changing the power
(zooming) by moving the optical elements, and so on.

The present optical system can be used as being
20 incorporated in the video camera, the still video
camera, the copier, or the like.

Each of the elements of the present embodiment
will be described in detail. In the non-coaxial, off-
axial, optical systems, as also described in Japanese
25 Patent Application Laid-open No. 9-5650, the reference
axis La does not agree with the normal to a component
surface in general, so that the optical power in the

plane P (YZ plane) including the reference axis La and the normal to surface is different from that in the plane Q (XY plane) including the normal to surface and being vertical to the plane P, even if curvatures of the surface are equal.

Accordingly, the component surfaces in the off-axial, optical system are normally anamorphic surfaces. When a component surface is anamorphic, it becomes possible to bring about astigmatism (on-axis astigmatism) independent of the field angle at all field angles, though no astigmatism appeared because of symmetry in the coaxial, rotationally symmetric systems.

Since this on-axis astigmatism is aberration that does not appear in the conventional, rotationally symmetric systems, it has little intensively been discussed heretofore in literatures and the like about the aberration theory. It will thus be discussed below. This on-axis astigmatism is aberration appearing independent of the field angle, and is aberration of a kind appearing in only systems lacking rotational symmetry.

This aberration is first-order aberration dependent on the first order of the pupil diameter but independent of the field angle. It is readily confirmed by optical tracing that this aberration is of the first order, and it is also possible to consider

that the optical powers differ depending upon azimuths in the case of the on-axis astigmatism. From the evaluation aspect for average power, it can also be intuitively understood that aberration appearing in the same order as defocus, i.e., aberration of the first order takes place at most azimuths.

Such on-axis astigmatism can be generated when the object-side imaging element and the image-side imaging element are anamorphic and have rotationally asymmetric powers. Since the off-axial, optical system has different powers even with the same curvature in two directions perpendicular to each other, such aberration is easy to generate.

Therefore, when this on-axis astigmatism appears in some quantity, degradation of the image (for example, the image on the intermediate image plane) is greater than by the rotationally symmetric, spherical aberration appearing in the third order of the pupil diameter in the conventional systems, and the effect equivalent to defocus can be achieved because the effect is of the first order.

This can readily be understood by description with the schematic diagram of lateral aberration on the intermediate image plane as shown in Fig. 8. Particularly, in dark optical systems the third-order aberration is slow to degrade the performance of intermediate imaging, whereas the first-order

aberration is more effective in achieving degradation than the third-order aberration, because the first-order aberration is of a slant, straight line, as indicated in this figure.

5 In the ordinary designing of optical system the system is designed so as to minimize (or reduce) aberration, whereas the present invention employs the reverse conception of generating as much aberration on the intermediate image plane 2 as possible.

10 Specifically, in the optical system of Figs. 1A and 1B in the present embodiment the surfaces 10-1, 10-2, 10-3 forming the object-side imaging element 10 are designed so as to have astigmatism (on-axis
15 astigmatism) independent of the field angle on the intermediate image plane 2 (the intermediate image plane 2 in the case of presence of the on-axis
astigmatism being defined by a middle position between two defocus positions where the spot is of a line
20 shape, for convenience' sake), as shown in the conceptual drawing of the spot diagram in Fig. 1B.

 Then the surfaces 11-1, 11-2, 11-3 forming the image-side imaging element 11 are designed so as to cancel the on-axis astigmatism. Namely, each of the object-side imaging element 10 and the image-side
25 imaging element 11 has the on-axis astigmatism singly, but the imaging optical system 5, which is the overall system comprised of the object-side imaging element 10

and the image-side imaging element 11, is an optical system corrected for aberration.

When the object-side imaging element 10 and the image-side imaging element 11 each include the astigmatism independent of the field angle (the on-axis astigmatism) as described above, even if there is a noise source such as the dust, bubble, or flaw near the intermediate image plane 2 (at or near the plane 2), the on-axis astigmatism prevents the noise source from eclipsing the all image information from the object points on the object plane 1; and the noise source is not imaged as a point on the final image plane 3 but is blurred by the on-axis astigmatism, thus flattening the (disturbance of) light intensity distribution on the image plane due to the noise source.

In general the size of the spot near the intermediate image plane 2 due to the on-axis astigmatism deliberately generated on the intermediate image plane 2 differs depending upon tolerance specifications of noise caused by the noise source, but it is two or more times, preferably three or more times, the size of the noise source posing the problem even at the minimum aperture value (which relates to the resolution of the image pickup device and which is given approximately by (Eq 1) described previously); in that case, since it is roughly estimated that an amount of light eclipsed by the noise source is proportional

to approximately the square of a ratio of diameters,
the amount of eclipsed light is not more than 25 %
(which is a closely permissible level though the effect
is recognized, from the empirical aspect), desirably
5 not more than 11 % (which is a level in which the
effect can be recognized first with attention, from the
empirical aspect), thereby achieving the effect of
flattening the disturbance of light intensity
distribution on the image plane due to the noise source
10 at the all aperture values. This means that for the
minimum resolution b given by the size of the pixels of
the image pickup device or the like, when β_{11}
represents the image magnification of the image-side
imaging element 11 in the case where the intermediate
15 image plane 2 is imaged on the final image plane 3 on
which the image pickup device is located, the size of
the spot, which is two or more times, desirably three
or more times, ((Eq 1) described previously), is
defined to be not less than the following:

20 $10 \cdot b / |\beta_{11}|$ (Eq 2);

desirably, not less than the following:

$15 \cdot b / |\beta_{11}|$ (Eq 3);

whereby the effect of flattening the disturbance of
light intensity distribution on the image plane due to
25 the noise source can be achieved at the all aperture
values.

Here, $|\beta_{11}|$ indicates the absolute value of the

image magnification β_{11} of the image-side imaging element 11.

In the case of a specification based on a completely different aspect, where the noise source becomes inoffensive at the full aperture of the stop, if the size of the spot near the intermediate image plane due to the on-axis astigmatism deliberately generated at the full aperture is three or more times, desirably five or more times, the size of the noise source posing the problem (which relates to the resolution of the image pickup device and which is given approximately by (Eq 1) described previously), the disturbance of light quantity due to the noise source can be controlled to about 11 % (which is a level in which the effect can be recognized first with attention, from the empirical aspect), desirably to approximately 4 % (which is a level in which the effect is little recognized even with attention, from the empirical aspect) with the stop being of the full aperture.

This means that for the minimum resolution b given by the size of the pixels of the image pickup device or the like, when β_{11} represents the image magnification of the image-side imaging element 11 where the intermediate image plane 2 is imaged on the final image plane 3 on which the image pickup device is located, the size of the spot, which is determined to be three

or more times, desirably five or more times, ((Eq 1)
described previously), is not less than the following:

$$15 \cdot b / |\beta_{11}| \quad (\text{Eq 4});$$

desirably, not less than the following:

5 $25 \cdot b / |\beta_{11}| \quad (\text{Eq 5});$

whereby the disturbance of light quantity due to the
noise source can be controlled to about 11 % (which is
a level in which the effect can be recognized first
with attention, from the empirical aspect), desirably
10 to about 4 % (which is a level in which the effect is
little recognized even with attention, from the
empirical aspect), with the stop being of the full
aperture.

Here, $|\beta_{11}|$ indicates the absolute value of the
15 image magnification β_{11} of the image-side imaging
element 11.

In this embodiment the description was focused on
the noise source of the type of Fig. 7B, but the same
can also be applied to the type of Fig. 7D (also
20 including the hollow type as well as the internally
solid type) and to the type of Fig. 7E.

The above discussion was given with the example
where the generated aberration was generated uniformly
at the all field angles, independent of the field
25 angles, for simplicity. In general, the important
point is that such a component is included as a bias
component, however. Therefore, the present invention

also involves systems in which an aberration component dependent on the field angle is overlaid, as long as the component uniformly generated at the all field angles without depending upon the field angle is included as a bias component and the above conditions for the size of spot are substantially satisfied at the all field angles.

Fig. 2A is a conceptual drawing to show a part of Embodiment 2 of the optical system according to the present invention. Fig. 2A illustrates a part of a cross section of an optical path diagram. Fig. 2B is an explanatory drawing to illustrate defocus characteristics of spot diagrams near the internal image plane 2.

In Fig. 2A the imaging optical system 5 is a non-coaxial, off-axial, optical system, and Fig. 2A illustrates only the vicinity of the intermediate image plane 2, because the optical path diagram is almost the same as Fig. 1A. As in Fig. 1A, the surfaces 10-1, 10-2, 10-3, forming the object-side imaging element 10, and the surfaces 11-1, 11-2, 11-3, forming the image-side imaging element 11, are integrally formed and the intermediate image plane 2 is located in the internally solid optical material.

The present embodiment is different from Embodiment 1 in the type of aberration deliberately generated at the intermediate image plane 2. In the

non-coaxial, off-axial, optical systems there generally exists aberration that appears independent of the field angle from on the axis to off the axis and by which rays in the meridional section jump out of the meridional section, called "aberration of torsion," in addition to the on-axis astigmatism.

In the present embodiment the imaging performance on the intermediate image plane 2 is degraded by generating this "aberration of torsion." This "aberration of torsion" does not appear in the conventional, rotationally symmetric systems, and will be described below in detail.

For example, if at least one of the component surfaces 10-1, 10-2, 10-3, 11-1, 11-2, 11-3 in Fig. 2A (thus in Fig. 1A) does not have symmetry with respect to the vertical direction in the plane of the drawing, even a group of rays having an equal azimuth on the surface of the entrance pupil 4 to an azimuth at the object point (they are called a ray group in the meridional section, which corresponds to a ray group included in the plane of Fig. 3A), after having passed the surface without symmetry, will not remain in the plane of meridional section and will change to those having "relation of torsion" as shown in Fig. 3B, in the three-dimensional space.

Therefore, the ray group in the mutual relation of torsion will not converge at a point. A group of

conical rays emerging from the same object point but passing different-azimuth portions of the pupil in the same pupil diameter also have the mutual relation of torsion in the three-dimensional space after having
5 passed through the surface without symmetry, so that the envelope composes a hyperboloid of one sheet as shown in Fig. 3C. Fig. 2B is a conceptual drawing of spot diagrams of such a ray group.

In general, this torsion is caused by a lack of
10 symmetry of the system and the smallest order of amounts of the torsion is the first order as it is readily checked by ray tracing. Accordingly, this "aberration of torsion" is also aberration of the first order dependent on the first order of the pupil
15 diameter. This aberration thus brings about greater degradation of intermediate imaging than the rotationally symmetric, spherical aberration occurring in the third order of the pupil diameter in the conventional systems, as shown in the schematic diagram
20 of lateral aberration in Fig. 8 and as was the case with the on-axis astigmatism. Since the effect of this aberration of torsion is of the first order, the effect is equivalent to that of defocus.

Specifically, this aberration can be generated by
25 absence of a common symmetry plane in the object-side imaging element and the image-side imaging element; that is, it can be produced when the elements have a

surface including the component of C_{11} in an equation representing the surface. It is apparent from inclusion of this C_{11} that the aberration is of the first order.

5 The component C_{11} is described in (Formula 1) in the specification of Japanese Patent Application Laid-open No. 9-5650. Specifically, in an optical system including a curved surface (off-axial curved surface), which is not a flat plane, wherein the normal to the
10 surface does not agree with the reference axis at an intersecting point between the curved surface and an optical path (the reference axis) of the reference-wavelength light traveling from the object plane to the image plane, the shape of the off-axial curved surface
15 is defined by the following formula starting from the second-order term in the coordinate system in which the origin is at the aforementioned intersecting point and the z-axis is taken along the normal to the surface.

$$\begin{aligned} z(x, y) = & C_{20}x^2 + 2C_{11}xy + C_{02}y^2 + D_{30}x^3 + 3D_{21}x^2y + 3D_{12}xy^2 + D_{03}y^3 \\ & + E_{40}x^4 + 4E_{31}x^3y + 6E_{22}x^2y^2 + 4E_{13}xy^3 + E_{04}y^4 + \dots \quad (\text{Formula 1}) \end{aligned}$$

20

It is natural that the intermediate image plane 2 in the system having such aberration should take such defocus that the diameter of the spot is the smallest. Employing this, the same argument can be made as in
25 Embodiment 1. (The "aberration of torsion" is independent of the field angle. This aberration is, however, aberration of the kind not appearing in the

rotationally symmetric systems.) In the normal designing of optical system the system is designed so as to eliminate as much aberration as possible, whereas this embodiment also adopts the reverse conception of generating as much aberration on the intermediate image plane 2 as possible.

Namely, in the optical system of Figs. 2A and 2B in the present embodiment, as shown in the conceptual drawing of the spot diagrams of Fig. 2B, the surfaces 10-1, 10-2, 10-3 forming the object-side imaging element 10 are designed so as to have the "aberration of torsion" appearing independent of the field angle on the intermediate image plane 2 and having such a property that the spot size is proportional to the pupil diameter.

Then the surfaces 11-1, 11-2, 11-3 forming the image-side imaging element 11 are designed so as to cancel the "aberration of torsion." Namely, each of the object-side imaging element 10 and the image-side imaging element 11 has the "aberration of torsion" singly, but the imaging optical system 5, which is the overall system comprised of the object-side imaging element 10 and the image-side imaging element 11, is an optical system corrected for aberration.

When the object-side imaging element 10 and the image-side imaging element 11 each include the "aberration of torsion" independent of the field angle

as described above, even if there is a noise source such as the dust, bubble, or flaw near the intermediate image plane 2, the "aberration of torsion" prevents the noise source from eclipsing the all image information from the object points on the object plane 1; and the noise source is not imaged as a point on the final image plane 3 but is blurred by the "aberration of torsion," thus flattening the (disturbance of) light intensity distribution on the image plane due to the noise source.

In general the size of the spot near the intermediate image plane due to the "aberration of torsion" deliberately generated on the intermediate image plane differs depending upon tolerance specifications of noise caused by the noise source; however, if the spot size is two or more times, preferably three or more times, the size of the noise source posing the problem at the minimum aperture value (which relates to the resolution of the image pickup device and which is given approximately by (Eq 1) described previously), it is roughly estimated that the amount of light eclipsed by the noise source is not more than 25 % (which is a closely permissible level though the effect is recognized, from the empirical aspect), desirably not more than 11 % (which is a level in which the effect can be recognized first with attention, from the empirical aspect), as in Embodiment

1, thereby achieving the effect of flattening the disturbance of light intensity distribution on the image plane due to the noise source at the all aperture values.

5 This means that for the minimum resolution b given
by the size of the pixels of the image pickup device or
the like, when β_{11} represents the image magnification
of the image-side imaging element 11 in the case where
the intermediate image plane 2 is imaged on the final
10 image plane 3 on which the image pickup device is
located, the size of the spot, which is two or more
times, desirably three or more times, ((Eq 1) described
previously), is defined to be not less than the
following:

15 $10 \cdot b / |\beta_{11}|$ (Eq. 2);

desirably, not less than the following:

$$15 \cdot b / |\beta_{11}| \quad (\text{Eq 3});$$

whereby the effect of flattening the disturbance of
light intensity distribution on the image plane due to
20 the noise source can be achieved at the all aperture
values.

Here, $|\beta_{11}|$ indicates the absolute value of the image magnification β_{11} of the image-side imaging element 11. In the case of a specification based on a completely different aspect, where the noise source becomes inoffensive at the full aperture of the stop, if the size of the spot near the intermediate image

plane due to the "aberration of torsion" deliberately generated at the full aperture is three or more times, desirably five or more times, the size of the noise source posing the problem (which relates to the resolution of the image pickup device and which is given approximately by (Eq 1) described previously), the disturbance of light quantity due to the noise source can be controlled to about 11 % (which is a level in which the effect can be recognized first with attention, from the empirical aspect), desirably to approximately 4 % (which is a level in which the effect is little recognized even with attention, from the empirical aspect) with the stop being of the full aperture.

This means that for the minimum resolution b given by the size of the pixels of the image pickup device or the like, when β_{11} represents the image magnification of the image-side imaging element 11 where the intermediate image plane 2 is imaged on the final image plane 3 on which the image pickup device is located, the size of the spot, which is determined to be three or more times, desirably five or more times, ((Eq 1) described previously), is not less than the following:

$$15 \cdot b / |\beta_{11}| \quad (\text{Eq 4});$$

desirably, not less than the following:

$$25 \cdot b / |\beta_{11}| \quad (\text{Eq 5});$$

whereby the disturbance of light quantity due to the

noise source can be controlled to about 11 % (which is a level in which the effect can be recognized first with attention, from the empirical aspect), desirably to about 4 % (which is a level in which the effect is
5 little recognized even with attention, from the empirical aspect), with the stop being of the full aperture. Here, $|\beta_{11}|$ indicates the absolute value of the image magnification β_{11} of the image-side imaging element 11.

10 In this embodiment the description was focused on the noise source of the type of Fig. 7B, but the same can also be applied to the type of Fig. 7D (also including the hollow type as well as the internally solid type) and to the type of Fig. 7E.

15 As one of higher-order aberration (which is the second order, higher in the order of dependence on the pupil diameter than the order of the "aberration of torsion") having the optical path diagram as shown in Fig. 2A, depending only on the pupil diameter but
20 independent of the field angle, and not appearing in the rotationally symmetric systems, there is on-axis coma (also called decentration coma), and this aberration has a weaker effect of defocus than the "aberration of torsion" by the difference of the higher
25 order. However, the effect is greater than the spherical aberration of the third order, which is the smallest order in the rotationally symmetric systems.

This aberration also has the effect of defocusing the intermediate image similarly in the sense that the aberration is asymmetric aberration appearing independent of the field angle. Therefore, the effect of this aberration is the same as in Embodiment 2.

Also in this embodiment, the above discussion was given with the example where the generated aberration was generated uniformly at the all field angles, independent of the field angles, for simplicity. In general, the important point is that such a component is included as a bias component, however. Therefore, the present invention also involves systems in which an aberration component dependent on the field angle is overlaid, as long as the component uniformly generated at the all field angles without depending upon the field angle is included as a bias component and the above conditions for the size of spot are substantially satisfied at the all field angles.

Figs. 4A, 4B, and 4C are conceptual drawings of major part of Embodiment 3 of the optical system according to the present invention. In this embodiment, the optical system involving the intermediate imaging is not a single lens but a zoom optical system. The zoom optical system as an off-axial, optical system corresponding to this embodiment is disclosed in Japanese Patent Application Laid-open No. 8-292372, wherein the image on the object plane 1

is formed by intermediate imaging and the intermediate image is imaged on the final image plane.

Figs. 4A, 4B, and 4C show sections of optical path diagram in Embodiment 3. The present embodiment is
5 expansion of the idea described in Embodiments 1 and 2 above to the zoom optical system and Figs. 4A, 4B, and 4C show an example of a three-unit zoom system in which the focal length, magnification, and focus of the final image plane are varied by relative movement of three
10 blocks indicated by the optical elements B1 to B3 in the direction of the reference axis La.

The present embodiment is the example in the structure wherein on the occasion of zooming from the wide-angle extreme to the telephoto extreme, the
15 optical element B1 is fixed, the optical element B2 moves back and forth along a convex locus in the positive direction of the Z-axis, the optical element B3 moves in the negative direction of the Z-axis, and the final image plane 3 is fixed. These diagrams do
20 not show defocus characteristics of spot diagrams near the three internal image planes 2-1, 2-2, 2-3 in the respective zoom states, but the characteristics are the same as in Embodiment 1 or in Embodiment 2.

In general, change in the focal length or change
25 in the image magnification will result in changing the position of the intermediate image plane therewith. Under such circumstances, unless the imaging

characteristics on the intermediate image plane are deliberately degraded, the noise source such as the dust, bubble, or flaw happens to be absent on the intermediate image plane at a certain focal length and at a certain image magnification and is thus inoffensive by chance in some cases, while the noise source often appears at another focal length and at another image magnification because of movement of the intermediate image plane in other cases.

10 The present embodiment thus employs the structure in which the imaging characteristics on the intermediate image planes are deliberately degraded in the all zoom states by utilizing freedom of asymmetry in the surface shapes of the off-axial, optical system and in which aberration is suppressed on the final image plane 3.

15 Generally speaking, this designing is possible because the off-axial, optical systems can use many coefficients expressing asymmetry, though values of the coefficients were 0 in the rotationally symmetric systems in terms of expression of surface. In general the size of the spot near the intermediate image plane due to the aberration independent of the field angle, deliberately generated on the intermediate image plane, differs depending upon tolerance specifications of noise caused by the noise source; however, if the spot size is two or more times, preferably three or more

times, the size of the noise source posing the problem at the minimum aperture value (which relates to the resolution of the image pickup device and which is given approximately by (Eq 1) described previously), it is roughly estimated that the amount of light eclipsed by the noise source is not more than 25 % (which is a closely permissible level though the effect is recognized, from the empirical aspect), desirably not more than 11 % (which is a level in which the effect can be recognized first with attention, from the empirical aspect), as in Embodiment 1, thereby achieving the effect of flattening the disturbance of light intensity distribution on the image plane due to the noise source at the all aperture values.

This means that for the minimum resolution b given by the size of the pixels of the image pickup device or the like, when β_{11} represents the image magnification of the image-side imaging element 11 in the case where the intermediate image plane 2 is imaged on the final image plane 3 on which the image pickup device is located, the size of the spot, which is two or more times, desirably three or more times, ((Eq 1) described previously), is defined to be not less than the following:

$$10 \cdot b / |\beta_{11}| \quad (\text{Eq 2});$$

desirably, not less than the following:

$$15 \cdot b / |\beta_{11}| \quad (\text{Eq 3});$$

whereby the effect of flattening the disturbance of light intensity distribution on the image plane due to the noise source can be achieved at the all aperture values.

5 Here, $|\beta_{11}|$ indicates the absolute value of the image magnification β_{11} of the image-side imaging element 11. In the case of a specification based on a completely different aspect, where the noise source becomes inoffensive at the full aperture of the stop, 10 if the size of the spot near the intermediate image plane due to the aberration independent of the field angle, deliberately generated at the full aperture is three or more times, desirably five or more times, the size of the noise source posing the problem (which 15 relates to the resolution of the image pickup device and which is given approximately by (Eq 1) described previously), the disturbance of light quantity due to the noise source can be controlled to about 11 % (which is a level in which the effect can be recognized first 20 with attention, from the empirical aspect), desirably to approximately 4 % (which is a level in which the effect is little recognized even with attention, from the empirical aspect), with the stop being of the full aperture.

25 This means that for the minimum resolution b given by the size of the pixels of the image pickup device or the like, when β_{11} represents the image magnification

of the image-side imaging element 11 where the intermediate image plane 2 is imaged on the final image plane 3 on which the photoreceptive surface of the image pickup device is located, the size of the spot, which is determined to be three or more times, desirably five or more times, ((Eq 1) described previously), is not less than the following:

$$15 \cdot b / |\beta_{11}| \quad (\text{Eq 4});$$

desirably, not less than the following:

$$10 \quad 25 \cdot b / |\beta_{11}| \quad (\text{Eq 5});$$

whereby the disturbance of light quantity due to the noise source can be controlled to about 11 % (which is a level in which the effect can be recognized first with attention, from the empirical aspect), desirably to about 4 % (which is a level in which the effect is little recognized even with attention, from the empirical aspect), with the stop being of the full aperture.

Here, $|\beta_{11}|$ indicates the absolute value of the image magnification β_{11} of the image-side imaging element 11. Also in this embodiment, the above discussion was given with the example where the generated aberration was generated uniformly at the all field angles, independent of the field angles, for simplicity. In general, the important point is that such a component is included as a bias component, however.

Therefore, the present invention also involves systems in which an aberration component dependent on the field angle is also overlaid, as long as a component uniformly generated at the all field angles without depending upon the field angle is included as a bias component and the above conditions for the size of spot are substantially satisfied at the all field angles.

In the description of the four embodiments so far, the discussion was mainly focused on the size of the noise source posing the problem in the range of about (Eq 1). This is because attention is given to the largest number of noise sources showing the influence, based on the fact that the number of noise sources such as dust particles present in the optical systems produced in controlled processes increases with decreasing diameter but quickly decreases with increasing diameter in general (see the schematic graph of Fig. 5).

In general, there are, however, noise sources sizes of which, posing the problem, are not less than (Eq 1). Generally, when a light reaches the final image plane without being eclipsed even in part, information is transmitted to the final image plane, aside from the issue of light quantity; when the spot diameter on the intermediate image plane is equal to the size of the noise source present at that position,

the light from the object plane is completely eclipsed, so that the information from the object plane is completely lost in that portion. It is hard to restore this completely lost information even by some process
5 such as image processing. Taking this point into account, let us explain the meaning of that the diameter of the spot on the intermediate image plane is "two or more times, desirably three or more times, at the minimum aperture" or "three or more times,
10 desirably five or more times, at the full aperture" larger than the diameter r_0 of the minimum noise source posing the problem, as described in the embodiments.

In general, increase in the spot diameter on the intermediate image plane means increase therewith in
15 the size of the noise source causing the complete loss of information. Taking account of the fact that the number of such noise sources as the dust particles existing in the optical systems produced in the controlled processes increases with decreasing size but
20 quickly decreases with increasing size as schematically shown in the graph of Fig. 5, the above means that the number of noise sources causing complete loss of information quickly decreases with increasing spot size on the intermediate image plane. (The hatched portion
25 in Fig. 5 corresponds to the number of noise sources causing complete loss of information where the spot size on the intermediate image plane is five times r_0 ,

and the number is quickly decreased when compared with the case where the spot diameter is r_0 .) This is equivalent to that the defective rate due to the noise sources of the imaging optical system is quickly
5 decreased with increasing spot size on the intermediate image plane.

Before explaining embodiments 4 to 9 of the present invention, let us next explain the way of expressing the component specifications of the optical
10 elements (also called optical systems) according to the present invention, and common items to the embodiments. Fig. 23 is an explanatory drawing for explaining the coordinate system for defining component data of the optical elements of the present invention. In the
15 optical elements of the present invention a surface at the i -th place along a ray traveling from the object side to the image plane (which is indicated by the chain line in Fig. 23 and which is called the reference-axis ray) is defined as the i -th surface. In
20 Fig. 23 the first surface R_1 is the stop, the second surface R_2 is a refractive surface coaxial with the first surface, the third surface R_3 is a reflective surface tilted relative to the second surface R_2 , the fourth surface R_4 and the fifth surface R_5 are
25 reflective surfaces each shifted and tilted relative to their preceding surface, and the sixth surface R_6 is a refractive surface shifted and tilted relative to the

fifth surface R5. The surfaces of the second surface R2 to the sixth surface R6 are formed on one optical element made of a medium such as glass or plastic material, which is the optical element 10 in Fig. 23.

5 In the structure of Fig. 23 the medium between the object plane not illustrated and the second surface R2 is air, the region between the second surface R2 and the sixth surface R6 is made of a common medium, and the medium from the sixth surface R6 to the seventh
10 surface R7 not illustrated is air.

 Since the optical elements of the present invention compose the off-axial, optical systems, the surfaces forming each of the optical elements share no common optic axis. Therefore, first set in the
15 embodiments of the present invention is an absolute coordinate system having the origin at the center of the ray-effective diameter of the first surface.

 In the embodiments of the present invention, the origin is defined at the center point of the ray-
20 effective diameter of the first surface and a path of a ray passing the origin and the center of the final image plane (the reference-axis ray) is defined as the reference axis of the optical system. Further, the reference axis in the embodiments has the direction
25 (orientation). The direction is one in which the reference-axis ray travels for imaging.

 Although the reference axis as the reference of

optical elements was set as described above in the
embodiments of the present invention, the axis for the
reference of the optical system can also be determined
to be any convenient axis in terms of optical design,
5 handling of aberration, or expression of each surface
shape forming the optical system. However, the
reference axis for the reference of the optical system
is normally set along a path of a ray passing the
center of the image plane and either one of the stop,
10 the entrance pupil, the exit pupil, the center of the
first surface of the optical system, and the center of
the final surface thereof.

Namely, in the embodiments of the present
invention, the reference axis is set along the path in
15 which the ray passing the center point of the ray-
effective diameter of the first surface or the stop
surface and reaching the center of the final image
plane (the reference-axis ray) is refracted and
reflected by the refractive surfaces and reflective
20 surfaces. The order of the surfaces is set according
to the order of refraction and reflection of the
reference-axis ray. Accordingly, the reference axis
changes its direction according to the law of
refraction or reflection along the order of the
25 surfaces thus set, to reach the center of the image
plane at last.

The tilt surfaces forming the optical element of

each embodiment of the present invention are basically tilted all in the same plane. The axes of the absolute coordinate system are thus defined as follows.

5 Z-axis: the reference axis passing the origin and directed to the second surface R2

 Y-axis: straight line passing the origin and making 90° counterclockwise with respect to the Z-axis in the tilt plane (in the plane of Fig. 23)

10 X-axis: straight line passing the origin and being perpendicular to each axis of Z and Y (straight line normal to the plane of Fig. 23)

 For expressing a surface shape of the i-th surface forming the optical element, recognition of shape becomes easier with a way of setting a local coordinate system with the origin at an intersecting point between the reference axis and the i-th surface and expressing the surface shape of the surface by the local coordinate system, rather than the way of expressing the surface shape by the absolute coordinate system.

15 Therefore, the surface shape of the i-th surface will be expressed by the local coordinate system in the embodiments described with component data of the present invention.

20 An angle of tilt of the i-th surface in the YZ plane is expressed by angle θ_i (in units of °), which is positive in the counterclockwise direction with respect to the Z-axis of the absolute coordinate

system. Therefore, the origin of the local coordinate system of each surface is placed on the YZ plane in Fig. 23 in the embodiments of the present invention. There is no decentration of the surfaces in the XZ plane and in the XY plane. Further, the y-axis and z-axis of the local coordinate system (x,y,z) of the i -th surface are inclined at the angle θ_i in the YZ plane with respect to the absolute coordinate system (X,Y,Z) , and the axes are set specifically as follows.

10 z-axis: straight line passing the origin of the local coordinate system and making the angle θ_i counterclockwise in the YZ plane with respect to the Z-direction of the absolute coordinate system

15 y-axis: straight line passing the origin of the local coordinate system and making 90° counterclockwise in the YZ plane with respect to the z-direction

 x-axis: straight line passing the origin of the local coordinate system and being perpendicular to the YZ plane

20 Further, D_i represents a scalar quantity indicating a distance between the origins of the local coordinate systems for the i -th surface and for the $(i+1)$ th surface, and N_{di} and v_{di} the refractive index and Abbe's number of a medium between the i -th surface and the $(i+1)$ th surface.

25 Each of the embodiments of the present invention will be described with a sectional view of the optical

element and the numerical data. For the optical system of Embodiment 8 of the preset invention described hereinafter, the overall focal length will be varied by movement of plural optical elements (i.e., the power is changed). In Embodiment 8 there are sectional views of the optical system at the three positions, the wide-angle extreme (W), the telephoto extreme (T), and a middle position (M) between them, and numerical data given.

10 In the optical element of Fig. 23, with movement of the optical element in the YZ plane the origins (Y_i, Z_i) of the local coordinate systems for expressing the positions of the respective surfaces vary so as to have different values at respective zoom positions.

15 Since in Embodiment 8 accompanied by the numerical data the optical elements moving for zooming are those moving only in the Z-direction, the coordinate values Z_i will be expressed by $Z_i(W)$, $Z_i(M)$, and $Z_i(T)$ in the order of the states at the wide-angle extreme, at the

20 middle position, and at the telephoto extreme of the optical system.

Coordinate values of each surface will be indicated by those at the wide-angle extreme, and values at the middle point and at the telephoto extreme

25 are described by differences from those at the wide-angle extreme. Specifically, when a and b represent movement amounts at the middle position (M) and at the

telephoto extreme (T), respectively, from the wide-angle extreme (W), the coordinate values Z_i thereat are expressed as follows.

$$Z_i(M) = Z_i(W) + a$$

5 $Z_i(T) = Z_i(W) + b$

Signs for a and b are determined to be positive for movement of each surface in the positive Z-direction but negative for movement in the negative Z-direction. A surface separation D_i varying with this movement is a variable and values at the respective zoom positions will be indicated together in another table.

10

The embodiments of the present invention has spherical surfaces and rotationally asymmetric, aspherical surfaces. For each spherical part among them, a radius of curvature R_i thereof will be given to express the spherical shape. The signs for the radius of curvature R_i are defined as follows; the sign is negative when the center of curvature is located on the first surface side along the reference axis directed from the first surface to the image plane (the chain line in Fig. 23); the sign is positive when the center of curvature is located on the image plane side.

15

20

Each spherical surface has the shape expressed by the following equation:

25

$$z = [(x^2 + y^2)/R_i] / [1 + \{1 - (x^2 + y^2)/R_i^2\}^{1/2}].$$

Each optical element of the present invention has

at least one rotationally asymmetric, aspherical surface, and the shape thereof is expressed by the following equation:

$$z=A/B+C02y^2+C20x^2+C03y^3+C21x^2y+C04y^4+C22x^2y^2+C40x^4,$$

5 where

$$A=(a+b) \cdot (y^2 \cdot \cos^2 t + x^2),$$

$$B=2a \cdot b \cdot \cos t [1 + \{(b-a) \cdot y \cdot \sin t / (2a \cdot b)\} + \{1 + \{(b-a) \cdot y \cdot \sin t / (a \cdot b)\} - \{y^2 / (a \cdot b)\} - \{4a \cdot b \cdot \cos^2 t + (a+b)^2 \sin^2 t\} x^2 / (4a^2 b^2 \cos^2 t)\}^{1/2}].$$

10 Since the above equation for curved surface includes only the terms of even powers with respect to x, curved surfaces defined by the above equation for curved surface have the shape of plane symmetry with respect to the symmetry plane of the yz plane. If the
15 following conditions are further satisfied, a curved surface has a shape symmetric with respect to the xz plane.

$$C03=C21=0 \text{ and } t=0$$

If the following conditions are further satisfied, a
20 curved surface has a rotationally symmetric shape.

$$C02=C20 \text{ and } C04=C40=C22/2$$

If the above conditions are not met, a curved surface has a rotationally asymmetric shape.

In each embodiment of the present invention the
25 first surface is the aperture stop, as shown in Fig. 23. A horizontal field angle u_Y is a maximum field angle of a light incident to the stop R1 in the YZ

plane of Fig. 23 and a vertical field angle u_X a maximum field angle of a light incident to the stop R1 in the XZ plane. The diameter of the stop R1 being the first surface will be indicated as an aperture

5 diameter. This relates to brightness of the optical system. Since the entrance pupil is located at the first surface, the above aperture diameter is equal to the diameter of the entrance pupil.

A range of an effective image on the image plane
10 will be indicated by an image size. The image size will be represented by a rectangular region having a horizontal length defined by a size in the y-direction of the local coordinate system and a vertical length defined by a size in the x-direction.

15 Lateral aberration diagrams will be given for each embodiment provided with component data. The lateral aberration diagrams show lateral aberrations of light at angles of incidence to the stop R1, (u_X, u_Y) , $(u_X, 0)$, $(u_X, -u_Y)$, $(0, u_Y)$, $(0, 0)$, $(0, -u_Y)$ as a combination of
20 vertical incidence angle and horizontal incidence angle, for each embodiment.

For Embodiment 8, lateral aberrations will be indicated in the states at the wide-angle extreme (W), at the middle position (M), and at the telephoto
25 extreme (T). In the lateral aberration diagrams the abscissa represents a height of incidence to the pupil and the ordinate an amount of aberration. Since in

each embodiment each surface is basically of a plane-symmetry shape with respect to the symmetry plane of the yz plane, the lateral aberration diagrams in the positive direction of the vertical field angle are the same as those in the negative direction, and thus the lateral aberration diagrams in the negative direction are omitted for simplicity of illustration.

The sizes of bubbles and particles posing the problem in terms of the optical performance, existing inside the optical element, or the widths of flaws or the sizes D of deposits etc. on the reflective surfaces, are approximately 10 to 100 μm . Let us keep on the description, assuming that the size D is 35 μm . The size D can be deemed as an inspection criterion mainly for determination of defective. Further, the description will be carried on assuming that the pixel size of CCD being the image pickup device is 6 μm square, i.e., that the resolution b is 6 μm .

If the width of the smallest spot is wider than the size of the bubble, particle, deposit, or the like, a decrease in light quantity due to the bubble, particle, deposit, or the like is determined by the area of the smallest spot and the area of the bubble, particle, deposit, or the like; if the width of the smallest spot is narrower than the size of the bubble, particle, deposit, or the like, the decrease in light quantity is determined by the length of the smallest

spot and the size of the bubble, particle, deposit, or the like.

Let us next explain meanings of Conditions (1a), (2a), (3a), (4a) described previously. The synthetic,
5 focal lengths were computed by reference to Japanese Patent Application Laid-open No. 9-5650. When the astigmatism independent of the field angle is generated, values of the focal length of the optical system vary depending upon azimuths.

10 Let f_{\max} be the maximum focal length out of those of the optical system in which the astigmatism independent of the field angle is generated, S be on-axis astigmatic difference, and R be the diameter of the exit pupil against the focal length f_{\max} . When the
15 light spot of on-axis rays first becomes linear, the length of the light spot can be expressed by the following.

$$\left| \frac{R \cdot S}{f_{\max}} \right|$$

20 Namely, the left side of Conditions (1a), (3a) represents a ratio of the size of the bubble, particle, or the like posing the problem, present in the optical element, or the width of flaw or the size of the deposit or the like on the reflective surface (D, or
25 $5b/|\beta|$) to the length of the linear light spot at the intermediate image position and at the full aperture. When the astigmatism independent of the field angle is

generated, the effect of the bubble, particle, deposit, or the like becomes maximum when the light spot is linear. Therefore, the smaller the left side of Conditions (1a), (3a), the smaller the decrease in light quantity due to the bubble, particle, deposit, or the like. Too small values of the left side of Conditions (1a), (3a) are not preferred in terms of aberration correction, however.

With astigmatism the light spot becomes linear twice, and the length of the light spot at occurrence of the first linear shape becomes shorter. Therefore, we must focus attention on the light spot at occurrence of the first linear shape. Conditions (2a), (4a) are those taking account of the cases of small apertures.

The level of the decrease in light quantity due to the bubble, particle, deposit, or the like varies depending upon the photosensitive material, the light receiving device, and so on, but the decrease in light quantity can be controlled to not more than 10 % at the full aperture when Conditions (1a), (2a) are satisfied; as long as the decrease in light quantity is about 10 %, the effect of the bubble, particle, deposit, or the like is inoffensive on the image. If Conditions (3a), (4a) are satisfied, the decrease in light quantity can be controlled to not more than 30 % at small apertures of the stop. As the diameter of small aperture becomes smaller and smaller, it becomes more difficult to

decrease the left side of Conditions (3a), (4a), as at the full aperture, and it is not preferred in terms of aberration correction. However, the decrease in light quantity of about 30 % can be corrected for on an
5 electrical basis, and the combination with the electrical correction enables the effect of the bubble, particle, deposit, or the like on the image to be reduced as at the full aperture of the stop.

Fig. 9 is a sectional view in the YZ plane of the
10 optical system of Embodiment 4 of the present invention. The present embodiment is a photographing optical system having the horizontal view angle of 63.4° and the vertical view angle of 49.6°. Fig. 9 also illustrates optical paths.

15 In the present embodiment the astigmatism independent of the field angle is generated at the intermediate image position and values of Conditions (1a), (3a) are calculated as follows.

$$\begin{aligned} \left| \frac{D \cdot f_1}{S \cdot AR_1} \right| &= \frac{0.035 \times 3.86}{0.79 \times 2} = 0.086 < 0.1 \\ \left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR_1} \right| &= \frac{0.030 \times 3.86}{0.98 \times 0.79 \times 2} = 0.075 < 0.1 \end{aligned}$$

20

The present embodiment thus satisfies Conditions (1a), (3a).

25 The component data of the present embodiment is as follows.

Half horizontal field angle 31.7

Half vertical field angle 24.8
Aperture diameter 2.00
Image size 4 mm horizontal × 3 mm vertical

	i	Yi	Zi	θi	Di	Ndi	vdi	
5	1	0.00	0.00	0.00	1.12	1		aperture stop
	2	0.00	1.12	0.00	7.49	1.58310	30.20	refractive surface
	3	0.00	8.61	18.49	9.86	1.58310	30.20	reflective surface
10	4	-5.93	0.73	0.58	9.30	1.58310	30.20	reflective surface
	5	-11.38	8.28	-16.00	8.90	1.58310	30.20	reflective surface
	6	-11.97	-0.61	-24.51	9.39	1.58310	30.20	reflective surface
15	7	-19.45	5.06	-26.42	8.02	1.58310	30.20	reflective surface
	8	-19.45	-2.96	0.00	3.68	1		refractive surface
	9	-19.45	-6.64	-0.00		1		image plane
Spherical shapes								
	R2 surface r2=-9.921							
20	R8 surface r8= 9.764							
Aspherical shapes								
	R3 surface a=-1.11675e+01 b=-1.26065e+01 t= 2.80750e+01							
	C03= 3.54262e-04 C21=-1.11331e-05							
	C04= 3.48452e-05 C22= 1.63301e-04 C40= 1.67279e-04							
25	R4 surface a=-2.52460e+00 b= 4.41616e+00 t=-3.55268e+01							
	C03=-4.00282e-03 C21=-5.33693e-03							
	C04= 1.64937e-03 C22= 1.34006e-03 C40=-5.90675e-04							

R5 surface $a=-6.17120e+00$ $b=1.69072e+01$ $t=-2.95634e+01$
C03= $-6.52258e-04$ C21= $-1.37521e-03$
C04= $2.48644e-05$ C22= $-1.37172e-04$ C40= $-1.48694e-04$
R6 surface $a=-9.06348e+02$ $b=-9.17518e+02$ $t=8.32864e+01$
5 C03= $9.11828e-04$ C21= $-2.36281e-05$
C04= $-7.11253e-05$ C22= $-4.01035e-04$ C40= $-4.11690e-04$
R7 surface $a=-1.95290e+01$ $b=-2.20227e+02$ $t=-1.50576e-01$
C03= $2.80664e-04$ C21= $-6.98915e-04$
C04= $5.82181e-07$ C22= $-7.51310e-05$ C40= $-1.54783e-04$

10

In Fig. 9 reference numeral 20 designates an optical element having a plurality of curved, reflective surfaces, which is made of a transparent body such as glass. In the surface of the optical
15 element 20 there are a concave, refractive surface (entrance surface) R2 having a negative refractive power, five reflective surfaces of concave mirror R3, convex mirror R4, concave mirror R5, reflective surface R6, and concave mirror R7, and a convex, refractive
20 surface (exit surface) R8 having a positive refractive power, formed in the order of passage of rays from the object. R1 represents the stop located on the object side of the optical element 20 and R9 the final image plane, on which the image pickup surface of the image
25 pickup device such as CCD is located. The two refractive surfaces are rotationally symmetric, spherical surfaces, and the all reflective surfaces are

surfaces symmetric only with respect to the YZ plane.

The object-side imaging element is defined by the region from the entrance surface R2 to the surface (R3) on the object side of the intermediate image plane, while the image-side imaging element by the region from the surface R4 to the final surface (R8) on the image side of the intermediate image plane. The same is also applicable to each of the embodiments described below.

The imaging action in the present embodiment will be described below. The light 21 from the object is regulated in the quantity of incident light by the stop (entrance pupil) R1 and thereafter it is incident to the entrance surface R2 of the optical element 20. Then the light is reflected by the surface R3 and thereafter is once focused between the surfaces R3 and R4. Then the light is reflected in order at the surfaces R4, R5, R6, R7 to emerge from the exit surface R8 and be again focused on the final image plane R9.

As described, the optical element 20 functions as a lens unit having desired optical performance and having a positive refractive power as a whole by the refractive powers of the entrance and exit surfaces and the refractive powers of the plurality of curved, reflective mirrors therein.

In the present embodiment, focusing to a near object is achieved by moving the whole of the optical element 20 relative to the image pickup surface R9 of

the image pickup device. Particularly, since the present embodiment is arranged so that the direction of the reference axis at the entrance of the optical element 20 is parallel to the direction of the reference axis at the exit of the optical element 20, the focusing operation can be performed by moving the whole optical element in parallel to the direction of the reference axis at the exit thereof (i.e., in the direction of the Z-axis), in the same manner as in the conventional lens systems. The lateral aberration diagrams of the optical element of the present embodiment are shown in Figs. 10A to 10L. It is seen that a well-balanced aberration correction state is achieved in the present embodiment.

The effect of the present embodiment will be described below. Fig. 24 illustrates on-axis and off-axis smallest spots near the intermediate image plane of the conventional reflecting optical system (optical element) shown in Fig. 6C. In this case, if a bubble or a particle having the size of $35\text{ }\mu\text{m}$ exists at the position of the smallest spot, the area of the on-axis smallest spot will be about $3535\text{ }\mu\text{m}^2$. Since the area of the bubble or particle having the size of $35\text{ }\mu\text{m}$ is about $962\text{ }\mu\text{m}^2$, the light quantity of about 27.2 % will be lost. On the other hand, the area of the off-axis smallest spot is about $9210\text{ }\mu\text{m}^2$, and it is thus understood that the light quantity of about 10.4 % is

lost. The decrease in light quantity due to the bubble or particle is smaller off the axis because of occurrence of greater aberration in the off-axis region.

5 Fig. 25 illustrates the on-axis and off-axis smallest spots near the intermediate image plane in Embodiment 4. If the bubble or particle having the size of $35\text{ }\mu\text{m}$ exists at the position of the smallest spot, judging from the figure, the area of the on-axis
10 smallest spot is about $11094\text{ }\mu\text{m}^2$ and the decrease in light quantity is about 8.7 %; while the area of the off-axis smallest spot is about $35487\text{ }\mu\text{m}^2$ and the decrease in light quantity is only about 2.7 %.

 When the size of the bubble or particle posing the
15 problem is defined to be $5b/|\beta|$, $5b/|\beta|=5\times 6/0.98=30.6\text{ }\mu\text{m}$, and the area is about $735\text{ }\mu\text{m}^2$. Therefore, the decrease in light quantity is about 6.6 % on the axis and about 2.1 % off the axis.

 Fig. 11 is a sectional view in the YZ plane of the
20 optical system of Embodiment 5 of the present invention. The present embodiment is a photographing optical system having the horizontal view angle of 63.4° and the vertical view angle of 49.6° . Fig. 11 also illustrates optical paths.

25 In the present embodiment the astigmatism independent of the field angle is generated at the intermediate image position. The present embodiment

takes account of the effect of the bubble or particle on the image at small apertures of the stop. In the present embodiment the F number at a small aperture is set to 8.

5 The left sides of Conditions (2a), (4a) are calculated as follows.

$$\left| \frac{D \cdot f_1}{S \cdot AR2} \right| = \frac{0.035 \times 4.06}{1.35 \times 0.405} = 0.26 < 0.3$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR2} \right| = \frac{0.03 \times 4.06}{0.96 \times 1.35 \times 0.405} = 0.23 < 0.3$$

10 Thus the present embodiment satisfies Conditions (2a), (4a).

 Further, the left sides of Conditions (1a), (3a) are calculated as follows.

15

$$\left| \frac{D \cdot f_1}{S \cdot AR1} \right| = \frac{0.035 \times 4.06}{1.35 \times 2} = 0.053 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 4.06}{0.96 \times 1.35 \times 2} = 0.047 < 0.1$$

 The present embodiment also satisfies Conditions (1a),
20 (3a) at the full aperture.

 The component data of the present embodiment is as follows.

Half horizontal field angle	31.7
25 Half vertical field angle	24.8
Aperture diameter	2.00
Image size	4 mm horizontal × 3 mm vertical

i	Yi	Zi	θi	Di	Ndi	vdi	
1	0.00	0.00	0.00	0.84	1		aperture stop
2	0.00	0.84	0.00	7.49	1.62191	45.07	refractive surface
3	0.00	8.33	18.49	9.86	1.62191	45.07	reflective surface
4	-5.93	0.45	0.58	9.30	1.62191	45.07	reflective surface
5	-11.38	8.00	-16.00	8.90	1.62191	45.07	reflective surface
6	-11.97	-0.89	-24.51	9.39	1.62191	45.07	reflective surface
7	-19.45	4.78	-26.42	8.02	1.62191	45.07	reflective surface
8	-19.45	-3.24	0.00	3.73	1		refractive surface
9	-19.45	-6.96	-0.00		1		image plane
Spherical shapes							
R2	surface r2=-9.401						
R8	surface r8=10.100						
Aspherical shapes							
R3	surface a=-1.14746e+01 b=-1.26394e+01 t= 3.26910e+01						
	C03= 4.07416e-04 C21=-6.56910e-05						
	C04=-2.83800e-05 C22= 2.03793e-04 C40= 2.56598e-04						
R4	surface a=-2.64358e+00 b= 4.22672e+00 t=-4.50100e+01						
	C03=-4.16081e-03 C21=-8.82585e-03						
	C04= 1.45602e-03 C22= 1.84420e-03 C40= 1.08907e-03						
R5	surface a=-6.18502e+00 b= 1.68729e+01 t=-3.02355e+01						
	C03=-7.11179e-04 C21=-1.41368e-03						
	C04= 5.16166e-05 C22=-1.42863e-04 C40=-1.46709e-04						
R6	surface a=-7.85347e+02 b=-7.93496e+02 t= 8.37924e+01						

C03= 8.07938e-04 C21= 1.69711e-04
C04=-8.35098e-06 C22=-4.44966e-04 C40=-5.08840e-04
R7 surface a=-1.90604e+01 b=-1.73227e+02 t=-7.44028e-01
C03= 3.37625e-04 C21=-5.13706e-04
5 C04= 4.72892e-05 C22=-9.63384e-05 C40=-2.04003e-04

In Fig. 11 reference numeral 20 designates an optical element having a plurality of curved, reflective surfaces, which is made of a transparent
10 body such as glass. In the surface of the optical element 20 there are a concave, refractive surface (entrance surface) R2 having a negative refractive power, five reflective surfaces of concave mirror R3, convex mirror R4, concave mirror R5, reflective surface
15 R6, and concave mirror R7, and a convex, refractive surface (exit surface) R8 having a positive refractive power, formed in the order of passage of rays from the object. R1 represents the stop located on the object side of the optical element 20 and R9 the final image
20 plane, on which the image pickup surface of the image pickup device such as CCD is located. The two refractive surfaces are rotationally symmetric, spherical surfaces, and the all reflective surfaces are surfaces symmetric only with respect to the YZ plane.
25 The imaging action in the present embodiment will be described below. The light 21 from the object is regulated in the quantity of incident light by the stop

(entrance pupil) R1 and thereafter it is incident to the entrance surface R2 of the optical element 20. Then the light is reflected by the surface R3 and thereafter is once focused between the surfaces R3 and R4. Then the light is reflected in order at the surfaces R4, R5, R6, R7 to emerge from the exit surface R8 and be again focused on the final image plane R9.

As described, the optical element 20 functions as a lens unit having desired optical performance and having a positive refractive power as a whole by the refractive powers of the entrance and exit surfaces and the refractive powers of the plurality of curved, reflective mirrors therein.

In the present embodiment, focusing to a near object is achieved by moving the whole of the optical system (optical element) relative to the image pickup surface R9 of the image pickup device. Particularly, since the present embodiment is arranged so that the direction of the reference axis at the entrance of the optical element 20 is parallel to the direction of the reference axis at the exit of the optical element 20, the focusing operation can be performed by moving the whole optical system in parallel to the direction of the reference axis at the exit thereof (i.e., in the direction of the Z-axis), in the same manner as in the conventional lens systems. The lateral aberration diagrams of the optical element of the present

embodiment are shown in Figs. 12A to 12L.

The effect of the present embodiment will be described below. Fig. 26 shows the on-axis and off-axis smallest spots near the intermediate image plane at the aperture of F/8 in the conventional reflecting optical system shown in Fig. 6C. In this case, if the bubble or particle having the size of $35\text{ }\mu\text{m}$ exists at the position of the smallest spot, almost all light quantity is lost on the axis and about 50 % of light quantity is lost off the axis when the length of the smallest spot is about $70\text{ }\mu\text{m}$, as seen from the figure. Fig. 27 shows the on-axis and off-axis smallest spots near the intermediate image plane at the aperture of F/8 in the present embodiment. When the bubble or particle having the size of $35\text{ }\mu\text{m}$ exists at the position of the smallest spot, judging from the figure, the length of the on-axis smallest spot becomes about $125\text{ }\mu\text{m}$ and the decrease in light quantity is about 28 %; the length of the off-axis smallest spot is about $125\text{ }\mu\text{m}$ and the decrease in light quantity is only about 28 %.

When the size of the bubble or particle posing the problem is defined to be $5b/|\beta|$, $5b/|\beta|=5\times 6/0.96=31.3\text{ }\mu\text{m}$, and the decreases in light quantity on the axis and off the axis both are about 25 %.

At a small aperture, it is difficult to decrease the left sides of Conditions (3a), (4a) as at the full

aperture, and it is not preferred in terms of aberration correction. It is, however, possible to effect electrical correction for the decrease in light quantity of about 30 %, and the effect on the image can be reduced by the combinational use of the electrical correction.

Fig. 13 is a sectional view in the YZ plane of the optical system of Embodiment 6 of the present invention. The present embodiment is a photographing optical system having the horizontal field angle of 63.4° and the vertical field angle of 49.6°. Fig. 13 also illustrates optical paths.

In the present embodiment the on-axis astigmatism, which is astigmatism independent of the field angle, is generated at the intermediate image position, and values of the conditions are calculated as follows.

$$\left| \frac{D \cdot f_1}{S \cdot AR_1} \right| = \frac{0.035 \times 3.34}{0.99 \times 1.62} = 0.073 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR_1} \right| = \frac{0.030 \times 3.34}{0.97 \times 0.99 \times 1.62} = 0.064 < 0.1$$

The present embodiment thus satisfies Conditions (1a), (3a).

The component data of the present embodiment is as follows. In the present embodiment the entrance surface is of a rotationally asymmetric surface shape.

Half horizontal field angle	31.7
Half vertical field angle	24.8

Aperture diameter 1.62

Image size 4 mm horizontal × 3 mm vertical

	i	Yi	Zi	θi	Di	Ndi	vdi	
5	1	0.00	0.00	0.00	2.25	1		aperture stop
	2	0.00	2.25	0.00	7.49	1.58310	30.20	refractive surface
	3	0.00	9.74	18.75	9.86	1.58310	30.20	reflective surface
	4	-6.00	1.92	1.04	9.27	1.58310	30.20	reflective surface
10	5	-11.37	9.47	-16.80	8.94	1.58310	30.20	reflective surface
	6	-11.65	0.53	-28.33	9.41	1.58310	30.20	reflective surface
	7	-19.67	5.45	-29.24	8.95	1.58310	30.20	reflective surface
15	8	-19.67	-3.51	0.00	4.10	1		refractive surface
	9	-19.67	-7.61	0.00		1		image plane

Spherical shape

R8 surface r8= 11.178

Aspherical shapes

20	R2 surface	a= ∞	b= ∞	t= 0
		C02=-8.40171e-02	C20=-5.56507e-03	
		C03= 0.00000e+00	C21= 0.00000e+00	
		C04= 8.39926e-04	C22=-1.25469e-03	C40= 2.31772e-04
	R3 surface	a=-1.13143e+01	b=-1.24404e+01	t= 1.58590e+01
25		C03= 7.85133e-05	C21= 6.09238e-05	
		C04= 2.73849e-05	C22= 8.98778e-05	C40= 9.20652e-05
	R4 surface	a=-2.26845e+00	b= 5.04617e+00	t=-2.74808e+01

C03= 8.07790e-04 C21=-2.78687e-03
C04= 5.10033e-05 C22= 7.62339e-04 C40=-7.53257e-04
R5 surface a=-6.11825e+00 b= 1.71331e+01 t=-2.13714+01
C03=-4.59621e-04 C21=-7.81713e-04
5 C04=-5.79810e-05 C22=-1.68453e-04 C40=-1.05899e-04
R6 surface a=-7.93207e+02 b=-7.93752e+02 t= 8.03054e+01
C03= 7.05489e-04 C21= 2.447661e-04
C04=-1.48850e-04 C22=-3.20082e-04 C40=-1.41576e-04
R7 surface a=-2.11107e+01 b=-1.23419e+03 t=-2.87104e+01
10 C03=-2.90841e-04 C21=-8.50288e-04
C04=-2.04956e-06 C22=-4.18670e-05 C40=-1.79566e-05

In Fig. 13 reference numeral 20 designates an optical element having a plurality of curved,
15 reflective surfaces, which is made of a transparent body such as glass. In the surface of the optical element 20 there are a concave, refractive surface (entrance surface) R2 having a negative refractive power, five reflective surfaces of concave mirror R3,
20 convex mirror R4, concave mirror R5, reflective surface R6, and concave mirror R7, and a convex, refractive surface (exit surface) R8 having a positive refractive power, formed in the order of passage of rays from the object. R1 represents the stop located on the object
25 side of the optical element 20 and R9 the final image plane, on which the image pickup surface of the image pickup device such as CCD is located. The exit surface

is a rotationally symmetric, spherical surface, and the all reflective surfaces are surfaces symmetric only with respect to the YZ plane.

5 The imaging action in the present embodiment will be described below. The light 1 from the object is regulated in the quantity of incident light by the stop (entrance pupil) R1 and thereafter it is incident to the entrance surface R2 of the optical element 20. Then the light is reflected by the surface R3 and
10 thereafter is once focused between the surfaces R3 and R4. Then the light is reflected in order at the surfaces R4, R5, R6, R7 to emerge from the exit surface R8 and be again focused on the final image plane R9.

15 As described, the optical element 20 functions as a lens unit having desired optical performance and having a positive refractive power as a whole by the refractive powers of the entrance and exit surfaces and the refractive powers of the plurality of curved, reflective mirrors therein.

20 In the present embodiment, focusing to a near object is achieved by moving the whole of the optical system relative to the image pickup surface R9 of the image pickup device. Particularly, since the present
25 embodiment is arranged so that the direction of the reference axis at the entrance of the optical element 20 is parallel to the direction of the reference axis at the exit of the optical system, the focusing

operation can be performed by moving the whole optical system in parallel to the direction of the reference axis at the exit thereof (i.e., in the direction of the Z-axis), in the same manner as in the conventional lens systems. The lateral aberration diagrams of the optical element of the present embodiment are shown in Figs. 14A to 14L.

The effect of the present embodiment will be described. Although the on-axis and off-axis smallest spots near the intermediate image plane are not illustrated especially, if the bubble or particle having the size $35\text{ }\mu\text{m}$ is present at the smallest spot position, the length of the smallest spot on the axis is about $470\text{ }\mu\text{m}$ and the decrease in light quantity is about 7.4 %; the length of the smallest spot off the axis is about $460\text{ }\mu\text{m}$ and the decrease in light quantity is only about 7.6 %.

When the size of the bubble or particle posing the problem is defined to be $5b/|\beta|$, $5b/|\beta|=5\times 6/0.97=30.9\text{ }\mu\text{m}$; thus, the decrease in light quantity on the axis is about 6.6 % and the decrease off the axis is about 6.7 %.

Further, since the entrance surface is of the rotationally asymmetric surface shape, the present embodiment is more likely to generate the on-axis astigmatism, which is the astigmatism independent of the field angle, at the intermediate image position

than in the case where the entrance surface is a
rotationally symmetric surface. Since the entrance
surface is arranged close to the entrance pupil, the
astigmatism can be generated almost uniformly against
5 the field angles.

Fig. 15 is a sectional view in the YZ plane of the
optical system of Embodiment 7 of the present
invention. The present embodiment is a photographing
optical system having the horizontal field angle of
10 63.4° and the vertical field angle of 49.6°. Fig. 15
also illustrates optical paths.

In the present embodiment the on-axis astigmatism,
which is astigmatism independent of the field angle, is
generated at the intermediate image position, and
15 values of the conditions are calculated as follows.

$$\left| \frac{D \cdot f_1}{S \cdot AR_1} \right| = \frac{0.035 \times 3.19}{1.21 \times 1.62} = 0.057 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR_1} \right| = \frac{0.030 \times 3.19}{1.01 \times 1.21 \times 1.62} = 0.048 < 0.1$$

The present embodiment thus satisfies Conditions (1a),
(3a).

The component data of the present embodiment is as
follows. In the present embodiment each of the
20 entrance surface and the exit surface is of a
rotationally asymmetric surface shape.

Half horizontal field angle 31.7

Half vertical field angle 24.8

Aperture diameter 1.62

Image size 4 mm horizontal × 3 mm vertical

	i	Yi	Zi	θi	Di	Ndi	vdi	
5	1	0.00	0.00	0.00	1.34	1		aperture stop
	2	0.00	1.34	0.00	7.49	1.58310	30.20	refractive surface
	3	0.00	8.82	18.75	9.86	1.58310	30.20	reflective surface
	4	-6.00	1.00	1.04	9.27	1.58310	30.20	reflective surface
10	5	-11.37	8.55	-16.80	8.94	1.58310	30.20	reflective surface
	6	-11.65	-0.39	-28.33	9.41	1.58310	30.20	reflective surface
	7	-19.67	4.53	-29.24	8.00	1.58310	30.20	reflective surface
15	8	-19.67	-3.47	0.00	3.76	1		refractive surface
	9	-19.67	-7.22	0.00		1		image plane

Aspherical shapes

	R2 surface	a= ∞	b= ∞	t= 0
20		C02=-1.72863e-01	C20=-3.43785e-02	
		C03= 0.00000e+00	C21= 0.00000e+00	
		C04=-1.14063e-02	C22=-2.25445e-02	C40=-6.18574e-03
	R3 surface	a=-1.16716e+01	b=-1.32422e+01	t= 3.13484e+00
		C03=-1.43087e-04	C21= 2.64110e-05	
		C04= 7.52835e-06	C22=-2.92736e-05	C40=-3.03489e-05
25	R4 surface	a=-2.40442e+00	b= 4.33821e+00	t= 1.33231e+01
		C03= 4.85362e-03	C21= 6.99637e-03	
		C04=-2.90654e-04	C22=-1.09311e-03	C40=-6.71405e-04

```

R5 surface a=-6.08378e+00    b= 1.77655e+01    t=-2.39551+01
      C03=-7.75363e-04 C21=-5.50043e-04
      C04=-1.00179e-04 C22=-2.64182e-04 C40=-1.49464e-04
5  R6 surface a=-4.05845e+02    b=-4.05368e+02    t= 8.32433e+01
      C03= 6.14312e-04 C21= 2.18334e-03
      C04=-2.16629e-04 C22=-8.99316e-04 C40=-5.26979e-04
R7 surface a=-1.84127e+01    b=-1.30993e+02    t= 3.36693e+01
      C03=-8.02648e-05 C21= 3.23663e-04
      C04= 1.45200e-05 C22=-3.16738e-04 C40=-1.89870e-04
10 R8 surface a= ∞            b= ∞            t= 0
      C02= 8.68816e-02 C20= 9.42024e-02
      C03= 0.00000e+00 C21= 0.00000e+00
      C04=-9.26017e-05 C22=-3.95347e-03 C40=-2.63504e-03

```

15 In Fig. 15 reference numeral 20 designates an optical element having a plurality of curved, reflective surfaces, which is made of a transparent body such as glass. In the surface of the optical element 20 there are a concave, refractive surface (entrance surface) R2¹ having a negative refractive power, five reflective surfaces of concave mirror R3, convex mirror R4, concave mirror R5, reflective surface R6, and concave mirror R7, and a convex, refractive surface (exit surface) R8 having a positive refractive power, formed in the order of passage of rays from the object. R1 represents the stop located on the object

side of the optical element 20 and R9 the final image plane, on which the image pickup surface of the image pickup device such as CCD is located. The all reflective surfaces are surfaces symmetric only with respect to the YZ plane.

5 The imaging action in the present embodiment will be described below. The light 1 from the object is regulated in the quantity of incident light by the stop (entrance pupil) R1 and thereafter it is incident to the entrance surface R2 of the optical element 20. Then the light is reflected by the surface R3 and thereafter is once focused between the surfaces R3 and R4. Then the light is reflected in order at the surfaces R4, R5, R6, R7 to emerge from the exit surface R8 and be again focused on the final image plane R9.

15 As described, the optical element 20 functions as a lens unit having desired optical performance and having a positive refractive power as a whole by the refractive powers of the entrance and exit surfaces and the refractive powers of the plurality of curved, reflective mirrors therein.

20 In the present embodiment, focusing to a near object is achieved by moving the whole of the optical system relative to the image pickup surface R9 of the image pickup device. Particularly, since the present embodiment is arranged so that the direction of the reference axis at the entrance of the optical element

25

20 is parallel to the direction of the reference axis at the exit of the optical system, the focusing operation can be performed by moving the whole optical system in parallel to the direction of the reference axis at the exit thereof (i.e., in the direction of the Z-axis), in the same manner as in the conventional lens systems. The lateral aberration diagrams of the optical element of the present embodiment are shown in Figs. 16A to 16L.

The effect of the present embodiment will be described. Although the on-axis and off-axis smallest spots near the intermediate image plane are not illustrated especially, if the bubble or particle having the size $35\text{ }\mu\text{m}$ is present at the smallest spot position, the area of the on-axis smallest spot is about $18600\text{ }\mu\text{m}^2$ and the decrease in light quantity is about 5.2 %; the area of the off-axis smallest spot is about $30800\text{ }\mu\text{m}^2$ and the decrease in light quantity is only about 3.1 %.

When the size of the bubble or particle posing the problem is defined to be $5b/|\beta|$, $5b/|\beta|=5\times 6/1.01=29.7\text{ }\mu\text{m}$; thus, the area is about $693\text{ }\mu\text{m}^2$, the decrease in light quantity on the axis is about 3.7 %, and the decrease off the axis is about 2.3 %.

Further, since the entrance surface is of the rotationally asymmetric surface shape, the present embodiment is more likely to generate the on-axis

astigmatism, which is the astigmatism independent of the field angle, at the intermediate image position than in the case where the entrance surface is a rotationally symmetric surface. Since the entrance surface is arranged close to the entrance pupil, the astigmatism can be generated almost uniformly against the field angles. Further, since the exit surface is of the rotationally asymmetric surface shape, the present embodiment can reduce occurrence of asymmetric aberration, such as distortion, produced at the entrance surface.

Figs. 17A to 17C are optical, sectional views in the YZ plane of Embodiment 8 of the present invention. Fig. 17A is a sectional view at the wide-angle extreme, Fig. 17B one at the middle position, and Fig. 17C one at the telephoto extreme. The present embodiment is a photographing optical system of a three-unit zoom lens comprised of three optical elements 22, 23, 24 and having the zoom ratio of about 3. The component data thereof is listed below.

In the present embodiment the astigmatism independent of the field angle is generated at the intermediate image position.

					wide-angle extreme	middle point	telephoto extreme
	Half horizontal field angle				26.3	13.9	9.3
	Half vertical field angle				20.3	10.5	7.0
5	Aperture diameter				1.30	2.60	3.86
	i	Yi	Zi(W)	θi	Di	Ndi	vdi
	1	0.00	0.00	0.00	2.00	1	aperture stop
	2	0.00	2.00	0.00	10.82	1.57250	57.76 refractive surface
10	3	0.00	12.82	32.01	10.00	1.57250	57.76 reflective surface
	4	-8.99	8.43	15.57	9.00	1.57250	57.76 reflective surface
	5	-13.87	15.99	-2.17	8.20	1.57250	57.76 reflective surface
15	6	-17.79	8.79	-14.41	8.70	1.57250	57.76 reflective surface
	7	-25.11	13.48	-28.67	5.50	1.57250	57.76 reflective surface
	8	-25.11	7.98	0.00	variable	1	refractive surface
	9	-25.11	7.10	0.00	5.70	1.57250	57.76 refractive surface
20	10	-25.11	1.40	25.00	7.50	1.57250	57.76 reflective surface
	11	-19.37	6.22	20.00	7.60	1.57250	57.76 reflective surface
	12	-18.05	-1.27	20.00	7.50	1.57250	57.76 reflective surface
25	13	-12.30	3.55	25.00	5.50	1.57250	57.76 reflective surface
	14	-12.30	-1.95	0.00	variable	1	refractive surface

	15-12.30	-8.76	0.00	7.00	1.57250	57.76	refractive surface			
5	16-12.30	-15.76	-28.09	9.80	1.57250	57.76	reflective surface			
	17-20.44	-10.31	-11.24	10.00	1.57250	57.76	reflective surface			
10	18-25.99	-18.63	-0.30	9.50	1.57250	57.76	reflective surface			
	19-31.35	-10.78	13.51	10.00	1.57250	57.76	reflective surface			
15	20-40.12	-15.58	30.67	7.00	1.57250	57.76	reflective surface			
20	21-40.12	-8.58	0.02	variable	1		refractive surface			
	22-40.12	-6.29	0.00	4.00	1.51633	64.15	refractive surface			
25	23-40.12	-2.29	0.00	1.00	1		refractive surface			
	24-40.12	-1.29	0.00		1		image plane			
30		wide-angle extreme		middle point			telephoto extreme			
	D8	0.89		5.36			7.69			
35	D14	6.81		4.55			3.37			
	D21	2.29		4.49			5.65			
40	D1-8 surfaces	$Z_i(M)=Z_i(W)+0.00$			$Z_i(T)=Z_i(W)+0.00$					
	D9-14 surfaces	$Z_i(M)=Z_i(W)-4.47$			$Z_i(T)=Z_i(W)-6.81$					
	D15-21 surfaces	$Z_i(M)=Z_i(W)-2.20$			$Z_i(T)=Z_i(W)-3.36$					
	D22 surface	$Z_i(M)=Z_i(W)$			$Z_i(T)=Z_i(W)$					
	Spherical shapes									
45	R2 surface	$r2 = -14.727$								
	R8 surface	$r8 = -7.999$								
	R9 surface	$r9 = -15.217$								

R14 surface r14= 8.191

R15 surface r15=-51.658

R21 surface r21= 6.898

R22 surface r22= ∞

5 R23 surface r23= ∞

Aspherical shapes

R3 surface C02=-1.94302e-02 C20=-3.52403e-02

C03=-6.05005e-05 C21= 3.34313e-04

C04=-2.64740e-05 C22=-5.50680e-05 C40=-6.85730e-05

10 R4 surface C02= 9.17779e-05 C20=-6.18233e-02

C03=-6.22285e-05 C21= 1.56326e-03

C04=-1.20412e-04 C22=-5.94589e-04 C40= 3.43423e-04

R5 surface C02=-1.79880e-02 C20=-4.47169e-02

C03=-2.19676e-04 C21=-3.43409e-05

15 C04=-4.20166e-05 C22=-1.02203e-04 C40=-1.42044e-04

R6 surface C02=-8.01208e-03 C20=-3.52443e-02

C03=-7.49991e-04 C21= 3.10102e-03

C04=-1.17900e-04 C22=-1.05389e-03 C40=-1.33235e-03

R7 surface C02=-2.51729e-02 C20=-3.30317e-02

20 C03=-2.07597e-04 C21= 1.88406e-04

C04=-2.43897e-05 C22=-8.46174e-05 C40=-2.65298e-05

R10 surface C02= 1.93480e-02 C20= 6.98052e-04

C03=-4.46652e-04 C21=-1.76685e-03

C04= 1.41004e-06 C22=-2.87544e-04 C40=-1.02043e-04

25 R11 surface C02=-1.77224e-02 C20=-2.86382e-02

C03=-8.52261e-04 C21=-1.67811e-03

C04=-1.40330e-04 C22=-1.73460e-05 C40=-8.74184e-07

R12 surface C02= 2.78627e-02 C20= 1.30724e-02
C03= 1.48986e-05 C21= 2.35448e-03
C04= 1.13038e-04 C22= 1.41561e-03 C40= 4.99584e-04

5 R13 surface C02=-3.52058e-02 C20=-9.12630e-02
C03= 2.06469e-03 C21= 4.97992e-03
C04= 9.30915e-05 C22=-5.25179e-04 C40=-1.07144e-04

R16 surface C02= 1.89481e-02 C20= 5.89085e-02
C03= 3.76913e-04 C21= 7.92483e-04
C04= 2.95432e-05 C22= 1.71436e-04 C40= 1.60251e-04

10 R17 surface C02=-8.27640e-03 C20=-2.90095e-02
C03= 4.98465e-04 C21=-8.54262e-03
C04= 4.17911e-05 C22=-8.35501e-04 C40=-2.96432e-04

R18 surface C02= 1.49383e-02 C20= 2.79447e-02
C03= 3.45413e-04 C21=-6.67856e-04
C04= 7.14602e-05 C22= 9.57676e-05 C40=-1.09444e-05

15 R19 surface C02=-2.78032e-03 C20= 3.47409e-03
C03= 3.05230e-04 C21=-1.29009e-03
C04= 1.34108e-04 C22= 6.74071e-05 C40=-1.81113e-05

R20 surface C02= 2.64689e-02 C20= 1.1119e-02
C03= 9.29169e-05 C21=-7.42810e-04
C04= 1.94555e-05 C22= 3.83296e-05 C40=-4.37073e-05

20

In Figs. 17A to 17C, the first surface R1 is the
stop surface of the entrance pupil, the second surface
R2 to the eighth surface R8 are the first optical
25 element 22, the ninth surface R9 to the fourteenth

surface R14 are the second optical element 23, and the fifteenth surface R15 to the twenty first surface R21 are the third optical element 24.

Numeral 25 designates an optical compensator
5 comprised of a plane-parallel plate, which is a low-pass filter, an infrared-cut filter, or the like made of quartz. The twenty third surface R23 is a surface of an image pickup device being the final image plane, which is, for example, an image pickup surface of CCD
10 (image pickup medium) or the like.

The imaging action will be described with the object at the infinity.

First, the light passing the first surface R1 is incident to the first optical element 22. In the first
15 optical element 22 the light is refracted by the second surface R2, reflected by the third surface R3, the fourth surface R4, the fifth surface R5, the sixth surface R6, and the seventh surface R7, and refracted by the eighth surface R8, then leaving the first
20 optical element 22. Here, intermediate imaging takes place near the fourth surface R4.

Then the light is incident to the second optical element 23. In the second optical element 23 the light is refracted by the ninth surface R9, reflected by the
25 tenth surface R10, the eleventh surface R11, the twelfth surface R12, and the thirteenth surface R13, and refracted by the fourteenth surface R14, then

leaving the second optical element 23. Here, the light has an intermediate image plane between the tenth surface R10 and the eleventh surface R11 and another intermediate image plane near the fourteenth surface R14.

Then the light emerging from the second optical element 23 is incident to the third optical element 24. In the third optical element 24 the light is refracted by the fifteenth surface R15, reflected by the sixteenth surface R16, the seventeenth surface R17, the eighteenth surface R18, the nineteenth surface R19, and the twentieth surface R20, and refracted by the twenty first surface R21, then leaving the third optical element 24. Here, intermediate imaging takes place near the eighteenth surface R18.

The light emerging from the third optical element 24 finally passes through the optical compensator 25 to be focused on the twenty third surface R23 being the final image plane.

Next described is movement of each optical element with the zooming operation. During the zooming operation the first optical element 22 is fixed, so as to be at a standstill. Zooming is achieved from the wide-angle extreme to the telephoto extreme by moving the second optical element 23 in the negative Z-direction. By moving the third optical element 23, variation of the image plane with zooming is corrected

for and focusing is achieved. The twenty third surface R23 being the image plane is stationary during zooming. The first optical element 22 corresponds to a so-called front lens of photographing optical system, the second
5 optical element 23 to a so-called variator, and the third optical element 24 to a compensator.

For the intermediate image positions near the fourth surface R4, near the tenth surface R10, near the fourteenth surface R14, and near the eighteenth surface
10 R18, values of Conditions (1a), (3a) are calculated as follows at the wide-angle extreme, at the middle position, and at the telephoto extreme. For the intermediate image position near the fourth surface R4, values of the conditions are calculated as follows.

15 At the wide-angle extreme, the values are as follows.

$$\left| \frac{D \cdot f1}{S \cdot AR1} \right| = \frac{0.035 \times 6.95}{2.46 \times 1.3} = 0.076 < 0.1$$
$$\left| \frac{5b \cdot f1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 6.95}{0.73 \times 2.46 \times 1.3} = 0.089 < 0.1$$

20 At the middle position, the values are as follows.

$$\left| \frac{D \cdot f1}{S \cdot AR1} \right| = \frac{0.035 \times 6.95}{2.46 \times 2.6} = 0.038 < 0.1$$
$$\left| \frac{5b \cdot f1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 6.95}{1.45 \times 2.46 \times 2.6} = 0.022 < 0.1$$

25 At the telephoto extreme, the values are as follows.

For the intermediate image position near the tenth

$$\left| \frac{D \cdot f1}{S \cdot AR1} \right| = \frac{0.035 \times 6.95}{2.46 \times 3.84} = 0.026 < 0.1$$

$$\left| \frac{5b \cdot f1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 6.95}{2.18 \times 2.46 \times 3.84} = 0.01 < 0.1$$

5 surface R10, the values of the conditions are calculated as follows.

At the wide-angle extreme, the values are as follows.

$$\left| \frac{D \cdot f1}{S \cdot AR1} \right| = \frac{0.035 \times 8.7}{2.99 \times 1.3} = 0.078 < 0.1$$

$$\left| \frac{5b \cdot f1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 8.7}{0.74 \times 2.99 \times 1.3} = 0.091 < 0.1$$

At the middle position, the values are as follows.

$$\left| \frac{D \cdot f1}{S \cdot AR1} \right| = \frac{0.035 \times 10.33}{5.96 \times 2.6} = 0.023 < 0.1$$

$$\left| \frac{5b \cdot f1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 10.33}{1.08 \times 5.96 \times 2.6} = 0.019 < 0.1$$

At the telephoto extreme, the values are as follows.

$$\left| \frac{D \cdot f1}{S \cdot AR1} \right| = \frac{0.035 \times 11.45}{7.8 \times 3.84} = 0.013 < 0.1$$

$$\left| \frac{5b \cdot f1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 11.45}{1.3 \times 7.8 \times 3.84} = 0.048 < 0.1$$

For the intermediate image position near the fourteenth surface R14, the values of the conditions are calculated as follows.

25 At the wide-angle extreme, the values are as follows.

At the middle position, the values are as follows.

$$\left| \frac{D \cdot f_1}{S \cdot AR1} \right| = \frac{0.035 \times 3.81}{1.21 \times 1.3} = 0.085 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 3.81}{1.2 \times 1.21 \times 1.3} = 0.061 < 0.1$$

5

$$\left| \frac{D \cdot f_1}{S \cdot AR1} \right| = \frac{0.035 \times 5.02}{1.23 \times 2.6} = 0.055 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 5.02}{1.67 \times 1.23 \times 2.6} = 0.028 < 0.1$$

At the telephoto extreme, the values are as follows.

10

$$\left| \frac{D \cdot f_1}{S \cdot AR1} \right| = \frac{0.035 \times 6.02}{1.33 \times 3.84} = 0.041 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 6.02}{1.92 \times 1.33 \times 3.84} = 0.018 < 0.1$$

15

For the intermediate image position near the eighteenth surface R18, the values of the conditions are calculated as follows.

At the wide-angle extreme, the values are as follows.

20

$$\left| \frac{D \cdot f_1}{S \cdot AR1} \right| = \frac{0.035 \times 3.65}{23.5 \times 1.3} = 0.004 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 3.65}{1.09 \times 23.5 \times 1.3} = 0.003 < 0.1$$

At the middle position, the values are as follows.

25

$$\left| \frac{D \cdot f_1}{S \cdot AR1} \right| = \frac{0.035 \times 7.1}{24.4 \times 2.6} = 0.004 < 0.1$$
$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR1} \right| = \frac{0.030 \times 7.1}{1.48 \times 24.4 \times 2.6} = 0.002 < 0.1$$

At the telephoto extreme, the values are as follows.

$$\left| \frac{D \cdot f_1}{S \cdot AR_1} \right| = \frac{0.035 \times 10.36}{24.55 \times 2.84} = 0.004 < 0.1$$

$$\left| \frac{5b \cdot f_1}{|\beta| \cdot S \cdot AR_1} \right| = \frac{0.030 \times 10.36}{1.73 \times 24.55 \times 3.84} = 0.002 < 0.1$$

The present embodiment thus satisfies Conditions (1a),
 5 (3a) under each of the above circumstances. In the present embodiment the aperture diameter decreases with zooming from the telephoto extreme to the wide-angle extreme. It thus becomes harder to satisfy the conditions at the wide-angle extreme.

10 Figs. 18A to 18L, Figs. 19A to 19L, and Figs. 20A to 20L are lateral aberration diagrams at the wide-angle extreme, at the middle position, and the telephoto extreme, respectively, of the present embodiment.

15 The effect of the present invention will be described. In order to avoid complexity, the decrease in light quantity due to the bubble or particle will be described only about on-axis rays at the wide-angle extreme.

20 Although the smallest spots are not illustrated especially, the lengths of the on-axis smallest spots are about 450 μm , about 440 μm , about 450 μm , and about 8.04 mm at the intermediate image positions near the fourth surface R4, near the tenth surface R10, near the
 25 fourteenth surface R14, and the eighteenth surface R18, respectively.

When the bubble or particle having the size of 35

μm exists at the respective smallest spot positions, the decrease in light quantity is only about 7.8 %, about 8 %, about 7.8 %, and about 0.4 % at the respective positions. Supposing the size of the bubble or particle posing the problem is $5b/|\beta|$, the sizes of the bubble or particle become 41.1 μm , 40.5 μm , 25 μm , and 27.5 μm at the respective intermediate image positions. When the bubble or particle is present at the smallest spot positions, the decrease in light quantity is only about 9.1 %, about 9.2 %, about 5.6 %, and about 0.3 % at the respective positions. The decrease in light quantity is further decreased with zooming from the wide-angle extreme to the telephoto extreme.

Fig. 21 is an optical, sectional view in the YZ plane of Embodiment 9 of the present invention. The present embodiment is a photographing optical system having the horizontal field angle of 38.2° and the vertical field angle of 29° . Fig. 21 also illustrates optical paths. The present embodiment employs a reflecting optical system comprised of a plurality of surface reflecting mirrors, instead of use of the optical element in which the refractive surfaces and reflective surfaces are formed in the surface of the transparent body.

In the present embodiment the astigmatism independent of the field angle is generated at the

intermediate image position, and values of Conditions (1a), (3a) are calculated as follows.

$$\left| \frac{D \cdot f_1}{S \cdot AR_1} \right| = \frac{0.035 \times 9.49}{2.76 \times 1.5} = 0.08 < 0.1$$

$$\left| \frac{5b \cdot f_1}{1\beta \cdot S \cdot AR_1} \right| = \frac{0.030 \times 9.49}{0.89 \times 2.76 \times 1.5} = 0.077 < 0.1$$

The present embodiment thus satisfies Conditions (1a), (3a).

The component data of the present embodiment is as follows.

Half horizontal field angle 19.1
Half vertical field angle 14.5
Aperture diameter 1.50

i	Yi	Zi	θi	Di	Ndi	vdi
1	0.00	0.00	0.00	6.91	1	aperture stop
2	0.00	6.91	28.00	10.05	1	reflective surface
3	-8.33	1.29	33.47	23.67	1	reflective surface
4	-3.84	24.53	33.00	8.85	1	reflective surface
5	-11.10	19.46	27.54	12.59	1	reflective surface
6	-11.10	32.05	0.00		1	image plane

Aspherical shapes

R2 surface a=-1.46039e+03 b=-8.02682e+00 t=-4.20029e+01
C03= 3.67405e-04 C21=-2.46091e-03
C04= 7.60473e-06 C22=-5.65605e-04 C40=-1.12101e-04

R3 surface $a = 1.26931e+01$ $b = 4.20864e+01$ $t = 3.49006e+01$
C03= $3.62552e-04$ C21= $4.25104e-03$
C04= $-1.54719e-04$ C22= $-4.16202e-04$ C40= $-1.06713e-04$
R4 surface $a = -2.61453e+02$ $b = -1.81578e+01$ $t = 2.33060e+01$
5 C03= $2.43935e-04$ C21= $6.87008e-05$
C04= $1.49521e-05$ C22= $-9.34036e-07$ C40= $1.30674e-05$
R5 surface $a = -2.21549e+01$ $b = 1.01587e+01$ $t = -2.84332e+00$
C03= $5.07372e-04$ C21= $8.89793e-04$
C04= $-2.95123e-06$ C22= $-6.31390e-05$ C40= $2.86129e-05$

10

The present embodiment is composed of the stop surface R1 as the entrance pupil, and four reflective surfaces including a concave mirror R2, a concave mirror R3, a concave mirror R4, and a concave mirror
15 R5, in the order of passage of rays from the object. R6 denotes the final image plane, at which the image pickup surface (photoreceptive surface) of the image pickup device such as CCD is located. The all reflective surfaces are surfaces symmetric only with
20 respect to the YZ plane.

The imaging action of the present embodiment will be described below. The light 1 from the object is regulated in the quantity of incident light by the stop (entrance pupil) R1 and thereafter reflected by the
25 reflective surface R2 to be focused once near the reflective surface R3. Then the light is reflected in order by the surfaces R3, R4, and R5 and thereafter is

again focused on the final image plane R6. Lateral aberration diagrams of the optical system of the present embodiment are shown in Figs. 22A to 22L.

5 The effect of the present embodiment will be described below. In the present embodiment a problem in the optical performance will be raised by the width of the flaw, the deposit, or the like on the reflective surface near the intermediate image position.

10 Fig. 28 shows the on-axis and off-axis light spots on the reflective surface near the intermediate image plane, i.e., on the third surface R3. In this case, if the deposit or the like having the size $35\text{ }\mu\text{m}$ is present on the third surface R3, the area of the on-axis light spot on the third surface R3 is about $72000\text{ }\mu\text{m}^2$ and the decrease in light quantity is about 1.3 %; 15 the area of the off-axis light spot on the third surface R3 is about $118800\text{ }\mu\text{m}^2$ and the decrease in light quantity is only about 0.8 %.

Supposing the size of the bubble or particle posing the problem is $5b/|\beta|$, $5b/|\beta|=5\times 6/0.89=33.7\text{ }\mu\text{m}$, 20 and the area is about $892\text{ }\mu\text{m}^2$; thus, the decrease in light quantity is about 1.2 % on the axis and the decrease is about 0.75 % off the axis. As described, the present embodiment can suppress the influence on 25 the image from the width of the flaw, deposit, or the like on the reflective surface near the intermediate image plane.

A reflection type zoom optical system can also be constructed by using a plurality of optical elements including the optical element(s) composed of plural reflective surfaces of the reflective mirrors as in Embodiment 9 and the optical element(s) in which two refractive surfaces and plural reflective surfaces are formed in the surface of the transparent body as in Embodiments 4 to 7, and changing the relative positions of at least two optical elements thereof to achieve zooming. In that case, the influence on the image can also be reduced from the bubble or particle present in the optical elements or from the flaw, deposit, etc. on the reflective surface near the intermediate image plane.

Another reflection type zoom optical system can also be constructed by using a plurality of optical elements including the optical element(s) in Embodiments 4 to 8 and coaxial, refracting optical element(s) composed of only refractive surfaces, and changing the relative positions of at least two optical elements thereof to achieve zooming. In that case, the influence on the image can also be reduced from the bubble or particle present in the optical elements or from the flaw, deposit, or the like on the reflective surface near the intermediate image plane.

As described above, in the optical apparatus in which intermediate imaging takes place at least once in

the optical path from the object to the final image plane, the lens system of the object-side imaging element and the lens system of the image-side imaging element for reimagining the intermediate image on the final image plane are properly set so as to flatten the disturbance of light intensity distribution due to the noise source on the final image plane even if the noise source is present at and near the intermediate image position, whereby the disturbance due to the noise becomes inoffensive on the image on the final image plane, thus achieving the optical element capable of obtaining a good image on the final image plane and the optical apparatus using it.

Particularly, in the optical apparatus having the optical element for forming the object image on the final image plane, which includes the object-side imaging element for forming the object image on the intermediate image plane at least once in the optical path before the final image plane and the image-side imaging element for reimagining the intermediate image on the final image plane, when the noise source is present at the position of the intermediate image plane, the disturbance of light intensity distribution due to the noise source is optically flattened on the final image plane, thereby achieving the effect of making the disturbance due to noise inoffensive on the image on the final image plane.

Particularly, when the means for flattening the disturbance of light intensity distribution due to the noise source is optical means for degrading the imaging performance at the intermediate image position, so as to flatten the disturbance of light intensity distribution on the image plane due to the noise source, the effect of making the disturbance due to noise inoffensive on the image on the final image plane can be achieved readily without increase in the number of components in particular.

Further, when the optical system is an off-axial, optical system wherein at least either of the object-side imaging element and the image-side imaging element includes an off-axial curved surface, the degrees of freedom increase on the optical arrangement of the off-axial, optical system (the off-axial, reflective surface is particularly ready for compact arrangement); and, in addition to the foregoing effect, the on-axis astigmatism or the "aberration of torsion," which was difficult to produce in the conventional, coaxial, rotationally symmetric, optical systems, can be generated easily, so that the effect of making the disturbance due to noise inoffensive on the image on the final image plane can be achieved more easily.

Generally speaking, the increase in the spot diameter on the intermediate image plane also brings about the effect that the defective rate of the optical

element due to the noise source can be quickly decreased.

As described above, in the optical element wherein the light from the object is made incident to the entrance surface formed in the surface of the transparent body, is reflected by at least one reflective surface of internal reflection comprised of a curved surface provided in a part of the transparent body, experiences intermediate imaging in the transparent body, and thereafter emerges from the exit surface of the transparent body to form the image or in the optical element wherein the light from the object is repetitively reflected by the plural reflective surfaces comprised of surface reflectors, experiences intermediate imaging, and thereafter emerges, at least either one surface includes an off-axial, reflective surface and the on-axis astigmatism or "aberration of torsion," which is the aberration independent of the field angle from on the axis to off the axis, is generated, so as to deliberately degrade the imaging performance at the intermediate image position relative to the imaging performance on the final image plane, thereby achieving the optical element having the effect of decreasing the influence on the image from the bubble or particle present in the optical element or from the flaw, deposit, etc. on the reflective surface near the intermediate image plane, and the image pickup

apparatus using it.

Particularly, by generating the on-axis astigmatism being the astigmatism independent of the field angle, the size of the light spot near the intermediate image plane can be relatively readily made
5 extremely larger than the size of bubble, particle, deposit, or the like posing the problem, thereby achieving the optical element having the effect of reducing the decrease in light quantity due to the
10 bubble or particle present inside or due to the flaw, deposit, etc. on the reflective surface, and the image pickup apparatus using it.

Further, when the entrance surface near the pupil has the rotationally asymmetric surface shape, the
15 astigmatism can be generated almost uniformly against the field angles, thereby achieving the optical element having the effect of reducing the influence on the image from the bubble or particle present in the optical element, almost uniformly against the field
20 angles, and the image pickup apparatus using it.

Further, when the exit surface also has the rotationally asymmetric surface shape, the optical element can be achieved with the effect of reducing occurrence of asymmetric aberration such as distortion
25 generated in the entrance surface, and the image pickup apparatus using it can also be achieved.

The first, curved, reflective surface, counted

from the object side, is provided with converging action, and this contributes to downsizing of the optical system. This is for making the optical system further thinner by intermediate imaging of pupil rays (principal rays) in the stage near the entrance surface, so that the off-axial, principal rays outgoing from the stop are converged before expanding large, thereby suppressing increase in the effective diameter of each surface after the first reflective surface due to wide-angle arrangement of the optical system.

The stop is located on the object side of the photographing optical system (or on the light incidence side of the optical system), and this suppresses increase in the size of the photographing optical system, which could result from wide-angle arrangement of the optical system.